NOTE: This is a section from our full Reducer Product Catalog. Page numbers are for reference only.
Excellent Technology for Evolving Industries

Harmonic Drive® actuators utilize high-precision, zero-backlash Harmonic Drive® precision gears and play critical roles in robotics, semiconductor manufacturing equipment, factory automation equipment, medical diagnostics and surgical robotics. Additionally, our products are frequently used in mission-critical spaceflight applications which capture the human spirit.

With over 50 years of experience, our expert engineering and production teams continually develop enabling technologies for the evolving motion control market. We are proud of our outstanding engineering capabilities and successful history of providing customer specific solutions to meet their application requirements.

Harmonic Drive LLC continues to develop enabling technologies for the evolving motion control market, which drives the pace of global innovation.

C. Walton Musser
Patented Strain Wave Gearing in 1955
Excellent Technology for Evolving Industries

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C. Walton Musser

Patented Strain Wave Gearing in 1955

Development of HarmonicDrive® Speed Reducers

Harmonic Drive® gears have been evolving since the strain wave gear was first patented in 1955. Our innovative development and engineering teams have led us to significant advances in our gear technology. In 1988, Harmonic Drive successfully designed and manufactured a new tooth profile, the “S” tooth. Since implementing the “S” tooth profile, improvement in life, strength and torsional stiffness have been realized. In the 1990s, we focused engineering efforts on designing gears featuring space savings, higher speed, higher load capacity and higher reliability. Then in the 2000s, significant reduction in size and thickness were achieved, all while maintaining high precision specifications.

Operating Principle of HarmonicDrive® Gears

A simple three-element construction combined with the unique operating principle puts extremely high reduction ratio capabilities into a very compact and lightweight package. The high-performance attributes of this gearing technology including, zero-backlash, high-torque-to-weight ratio, compact size, and excellent positional accuracy, are a direct result of the unique operating principles.

Wave Generator
The Wave Generator is a thin, raced-ball bearing fitted onto an elliptical hub. This serves as a high-efficiency torque converter and is generally mounted onto the input or motor shaft.

Flexspline
The Flexspline is a non-rigid, thin cylindrical cup with external teeth on the open end of the cup. The Flexspline fits over the Wave Generator and takes on its elliptical shape. The Flexspline is generally used as the output of the gear.

Circular Spline
The Circular Spline is a rigid ring with internal teeth. It engages the teeth of the Flexspline across the major axis of the Wave Generator ellipse. The Circular Spline has two more teeth than the Flexspline and is generally mounted onto a housing.

The Flexspline is slightly smaller in diameter than the Circular Spline and usually has two fewer teeth than the Circular Spline. The elliptical shape of the Wave Generator causes the teeth of the Flexspline to engage the Circular Spline at two opposite regions across the major axis of the ellipse.

As the Wave Generator rotates the teeth of the Flexspline engage with the Circular Spline at the major axis.

For every 180 degree clockwise movement of the Wave Generator, the Flexspline rotates counterclockwise by one tooth in relation to the Circular Spline.

Each complete clockwise rotation of the Wave Generator results in the Flexspline moving counterclockwise by two teeth from its original position, relative to the Circular Spline. Normally, this motion is taken out as output.

Development of HarmonicDrive® Speed Reducers

Harmonic Drive® gears have been evolving since the strain wave gear was first patented in 1955. Our innovative development and engineering teams have led us to significant advances in our gear technology. In 1988, Harmonic Drive successfully designed and manufactured a new tooth profile, the “S” tooth. Since implementing the “S” tooth profile, improvement in life, strength and torsional stiffness have been realized. In the 1990s, we focused engineering efforts on designing gears featuring space savings, higher speed, higher load capacity and higher reliability. Then in the 2000s, significant reduction in size and thickness were achieved, all while maintaining high precision specifications.
Component Set FB

1. Types of lubricant
2. Oil quantity
3. When to replace oil

First time 100 hours after starting operation
Second time and after Every 1000 operation hours or every 6 months.

Note that you should replace the oil earlier than specified if the operating condition is demanding.

Different from oil lubrication, as a cooling effect is not expected from grease lubrication, it is only available for short operation.

Component Set FR

112
113
115
116
119
120
121

Table 110-1

There are two types of lubrication oil lubrication and grease lubrication. Although oil lubrication is common, grease lubrication is applicable to intermittent operation.

Oil level should be maintained at the level as shown. Figure 110-1.

See page 18 for details of the lubricant.

Oil level position

Unit: mm

Fig. 110-1

NOTE: This is a section from our full Reducer Product Catalog. Page numbers are for reference only.
Features

FR series component type
FR is a heavy duty pancake gear that uses a double wave generator bearing. It consists of four parts like the FB series and operates using the same principle as the cup type. It is basically structured in the same way as the FB series and supports high torque capacity by arranging the wave generator bearings in two lines and widening the tooth width of the circular spline and the flexspline.

Features
- Flat and thin shape
- High torque capacity
- Compact and simple design
- High positional and rotational accuracies
- Coaxial input and output

Structure of the FR series component type

Circular spline D
It has the same number of teeth as the flexspline. As it generates no relative rotation with the flexspline, it rotates at the same speed as the flexspline.

Circular spline S
It has two more teeth than the flexspline like the cup-type circular spline.

* How to tell circular spline D from circular spline S
The peripheral chamfering of circular spline D is larger than that of circular spline S.
### Ordering Code

**FR - 20-80 - 2 - GR**

**Table 113-1**

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<th>Series</th>
<th>Size</th>
<th>Ratio*</th>
<th>Model</th>
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</tbody>
</table>

* The reduction ratio value is based on the following configuration:
  Input: wave generator, fixed: circular spline, output: flexspline

---

### Rotational direction and reduction ratio

**Fig. 113-1**

1. **Reducer**
   - Input: Wave Generator
   - Output: Circular Spline D
   - Fixed: Circular Spline S
   - Rotational direction: Input: D, Output: S
   - Reduction ratio: \( i = \frac{1}{R} \)

2. **Reducer**
   - Input: Wave Generator
   - Output: Circular Spline S
   - Fixed: Circular Spline D
   - Rotational direction: Input: D, Output: S
   - Reduction ratio: \( i = \frac{1}{R+1} \)

3. **Reducer**
   - Input: Circular Spline D
   - Output: Wave Generator
   - Fixed: Circular Spline S
   - Rotational direction: Input: S, Output: D
   - Reduction ratio: \( i = R+1 \)

4. **Overdrive**
   - Input: Circular Spline S
   - Output: Wave Generator
   - Fixed: Circular Spline D
   - Rotational direction: Input: S, Output: D
   - Reduction ratio: \( i = R+1 \)

5. **Overdrive**
   - Input: Circular Spline S
   - Output: Wave Generator
   - Fixed: Circular Spline D
   - Rotational direction: Input: S, Output: D
   - Reduction ratio: \( i = R+1 \)

6. **Overdrive**
   - Input: Circular Spline D
   - Output: Wave Generator
   - Fixed: Circular Spline S
   - Rotational direction: Input: S, Output: D
   - Reduction ratio: \( i = R \)

7. **Differential**
   - When all of the Wave Generator, the Circular Spline S and the Circular Spline D rotate, Combinations (1) through (6) are available.
## Technical Data

### Gearheads & Actuators

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<th>Max. Average Load Torque</th>
<th>Max. Momentary Torque</th>
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*Torque value limited by ratcheting.

1. Moment of Inertia: \( J = \frac{l^2}{3}GD^2 \)

2. See Rating Table Definitions on Page 12 for details of the terms.

Load Inertia = J
Engineering Data

Component Sets

Gear Units

Phase Adjusters

Gearheads & Actuators

Engineering Data

Component Type

Unit Type

Gear Head Type

Differential Gear

Load inertia = J

2. See Rating Table Definitions on Page 12 for details of the terms.

※

Table 115-1

Dimensions

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Unit: mm

I

M3×6 | M3×8 | M4×8 | M5×10 | M6×12 | M8×16 | M10×20 | M10×20 | M12×24

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<td>N</td>
<td>c0.2</td>
<td>c0.2</td>
<td>c0.2</td>
<td>c0.2</td>
<td>c0.4</td>
<td>c0.4</td>
<td>c0.4</td>
<td>c0.4</td>
</tr>
<tr>
<td>øV</td>
<td>39</td>
<td>42</td>
<td>53</td>
<td>69</td>
<td>84</td>
<td>105</td>
<td>138</td>
<td>169</td>
</tr>
<tr>
<td>øU</td>
<td>5.75</td>
<td>31.5</td>
<td>3.1</td>
<td>1.5</td>
<td>1.5</td>
<td>1.5</td>
<td>0.4</td>
<td>1.5</td>
</tr>
<tr>
<td>øV</td>
<td>32</td>
<td>32</td>
<td>32</td>
<td>32</td>
<td>44</td>
<td>52</td>
<td>58</td>
<td></td>
</tr>
<tr>
<td>øW</td>
<td>4.8</td>
<td>6.1</td>
<td>7.6</td>
<td>9.8</td>
<td>12.6</td>
<td>16</td>
<td>19.7</td>
<td></td>
</tr>
<tr>
<td>øX</td>
<td>1.6</td>
<td>1.9</td>
<td>2.5</td>
<td>3.2</td>
<td>4.4</td>
<td>5.1</td>
<td>6.3</td>
<td></td>
</tr>
<tr>
<td>Z</td>
<td>R0.08 to 0.16</td>
<td>R0.08 to 0.16</td>
<td>R0.08 to 0.25</td>
<td>R0.08 to 0.25</td>
<td>R0.08 to 0.25</td>
<td>R0.08 to 0.25</td>
<td>R0.08 to 0.25</td>
<td></td>
</tr>
</tbody>
</table>

Mass kgf

| 0.2 | 0.5 | 0.8 | 1.7 | 3.0 | 6.0 | 12.0 | 22.3 | 42.6 |

(Note) For Circular spline D, the peripheral chamfering is M.

*The C, D and F values indicate relative position of individual gearing components (wave generator, flexspline, circular spline). Please strictly adhere to these values when designing your housing and mating parts.

Four parts (wave generator, flexspline, circular spline D, circular spline S) are not assembled when delivered.
Efficiency

The efficiency varies depending on the following conditions.
- Reduction ratio
- Input rotational speed
- Load torque
- Temperature
- Lubrication (Type and quantity)

Efficiency compensation coefficient

If the load torque is lower than the rated torque, the efficiency will be lower. Calculate the compensation coefficient Ke from Graph 116-1 to calculate the efficiency using the following example.

Calculation Example

Efficiency η (%) under the following condition is calculated from the example of FR-20-80-2GR.
- Input rotational speed: 1000 rpm
- Load torque: 19.6 Nm
- Lubrication: Grease lubrication (Harmonic Grease SK-1A)
- Lubricant temperature: 20°C
Since the rated torque of size 20 with a reduction ratio of 80 is 34 Nm (Ratings: Page 114), the torque ratio α is 0.58.
(α=19.6/34=0.58)

- The efficiency compensation coefficient is Ke=0.86 from Graph 116-1.
- Efficiency η at load torque 19.6 Nm: η=Ke×ηR=0.86 x 65=56%
### Efficiency at rated torque (oil lubrication)

#### Graph 117-1
- **Input speed:** 500rpm
- **Graph:** Efficiency (%)
- **Ambient Temperature (ºC):** -10 to 40
- **Efficiency (%)**
  - Ratio
  - 50,80
  - 120
  - 160
  - 200
  - 260
  - 320

#### Graph 117-2
- **Input speed:** 1000rpm
- **Graph:** Efficiency (%)
- **Ambient Temperature (ºC):** -10 to 40
- **Efficiency (%)**
  - Ratio
  - 50,80
  - 120
  - 160
  - 200
  - 260
  - 320

#### Graph 117-3
- **Input speed:** 2000rpm
- **Graph:** Efficiency (%)
- **Ambient Temperature (ºC):** -10 to 40
- **Efficiency (%)**
  - Ratio
  - 50,80
  - 120
  - 160
  - 200
  - 260
  - 320

#### Graph 117-4
- **Input speed:** 3500rpm
- **Graph:** Efficiency (%)
- **Ambient Temperature (ºC):** -10 to 40
- **Efficiency (%)**
  - Ratio
  - 50,80
  - 120
  - 160
  - 200
  - 260
  - 320

---

**Calculation Example**

The efficiency varies depending on the following conditions.

- Reduction ratio
- Input rotational speed
- Load torque
- Temperature
- Lubrication (Type and quantity)

If the load torque is lower than the rated torque, the efficiency will be lower. Calculate the compensation coefficient $K_e$ from Graph 116-1 to calculate the efficiency using the following example.

**Efficiency compensation coefficient**

Efficiency $\eta$ (%) under the following condition is calculated from the example of FR-20-80-2GR.

- **Input rotational speed:** 1000 rpm
- **Load torque:** 19.6 Nm
- **Lubrication:** Grease lubrication (Harmonic Grease SK-1A)
- **Lubricant temperature:** 20°C

Since the rated torque of size 20 with a reduction ratio of 80 is 34 Nm (Ratings: Page 114), the torque ratio $\alpha$ is 0.58.

$$\alpha = \frac{19.6}{34} = 0.58$$

The efficiency compensation coefficient $K_e = 0.86$ from Graph 116-1.

**Efficiency $\eta$ at load torque 19.6 Nm:**

$$\eta = K_e \cdot \eta_R = 0.86 \times 65\% = 56\%$$
**Efficiency at rated torque (grease lubrication)**

**Input speed: 500rpm**

- **Graph 118-1**

**Input speed: 1000rpm**

- **Graph 118-2**

**Input speed: 2000rpm**

- **Graph 118-3**

**Input speed: 3500rpm**

- **Graph 118-4**
No-load running torque, starting torque, backdriving torque

Values indicated are from actual tests with the component sets assembled in their housings, and inclusive of friction resistance of oils seals, and churning of oil.

(1) No-load running torque--- No-load running torque is the torque which is required to rotate the input side (high speed side), when there is no load on the output side (low speed side). The value in the graph indicates the condition when the input rotational speed is 1500 rpm and the oil temperature is about 40°C.

(2) Starting torque ----------- This is the static torque required to start the high-speed shaft in a no-load condition.

(3) Backdriving torque -------- This is the static torque required to start the low-speed shaft in a no-load condition.
Lost motion and the spring constant

Lost motion and the spring constant of the pancake gear is the value when the wave generator or one circular spline is fixed and when a torque is applied to the dynamic spline.

Table 120-1

<table>
<thead>
<tr>
<th>Size (mm)</th>
<th>Lost motion (arc min)</th>
<th>Spring constant (kgf/min)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>a Load (kgf)</td>
<td>Standard product</td>
</tr>
<tr>
<td>14</td>
<td>0.04</td>
<td>≈ 3.0</td>
</tr>
<tr>
<td>20</td>
<td>0.12</td>
<td>3.0</td>
</tr>
<tr>
<td>25</td>
<td>0.23</td>
<td>3.0</td>
</tr>
<tr>
<td>32</td>
<td>0.46</td>
<td>3.0</td>
</tr>
<tr>
<td>40</td>
<td>0.92</td>
<td>3.0</td>
</tr>
<tr>
<td>50</td>
<td>1.73</td>
<td>3.0</td>
</tr>
<tr>
<td>65</td>
<td>3.9</td>
<td>3.0</td>
</tr>
<tr>
<td>80</td>
<td>7.4</td>
<td>3.0</td>
</tr>
<tr>
<td>100</td>
<td>14.4</td>
<td>3.0</td>
</tr>
</tbody>
</table>

■ Description on lost motion and spring constant

When assembled, rotation of the Wave Generator as a high speed input member imparts a rotating elliptical shape to the Flexspline. This causes progressive engagement of its external teeth with the internal teeth of the Circular Spline. The fixed Circular Spline, having a larger number of teeth than the Flexspline causes the latter to precess at a rate determined by the ratio of tooth difference to the total number of teeth. With the same number of teeth as the Flexspline, the Dynamic Spline rotates with, and at the same speed as, the Flexspline and is the output member of the drive.

(1) Lost motion (L/M)

The lost motion is the total value of rotational angle of low-speed shaft when the high-speed shaft is fixed in rotational direction with the drive installed and when slight load torque (see Table 120-1) is applied to the low-speed shaft the other way round.

(2) Spring constant

By increasing the load torque gradually in the same manner as the lost motion and applying the load the other way round, "load torque - torsional angle" diagram emerges as shown in Fig. 120-2. The average spring constant obtained by this diagram is shown in Table 120-1. (This value is only for the HarmonicDrive® components.)

■ Example of calculation

Use model number FR-40-160-2A-GR to fix the input shaft in rotational direction, and apply the load (30kgf) rated in the catalog to the output shaft, and then obtain the torsional angle.

\[ \theta = \frac{L \cdot M}{2} + \frac{1}{K} (T - T_{LM}) \]

\[ = 1.5 + \frac{1}{7.8} (30 - 0.92) \]

\[ = 5.23 \text{ arc min} \]

Maximum value *θ* max when rotated the other way round is

\[ \theta_{\text{max}} = 2 \cdot \theta = 10.46 \text{ arc min} \]
Recommended tolerances for assembly

Maintain the recommended assembly tolerances shown in Figure 121-1 and Table 121-1 for maximum performance of your FR gear.

![Diagram](image)

**Recommended tolerances for assembly**

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Size</th>
<th>14</th>
<th>20</th>
<th>25</th>
<th>32</th>
<th>40</th>
<th>50</th>
<th>65</th>
<th>80</th>
<th>100</th>
</tr>
</thead>
<tbody>
<tr>
<td>a</td>
<td></td>
<td>0.013</td>
<td>0.017</td>
<td>0.024</td>
<td>0.026</td>
<td>0.026</td>
<td>0.028</td>
<td>0.034</td>
<td>0.043</td>
<td>0.057</td>
</tr>
<tr>
<td>b</td>
<td></td>
<td>0.015</td>
<td>0.016</td>
<td>0.016</td>
<td>0.017</td>
<td>0.019</td>
<td>0.024</td>
<td>0.027</td>
<td>0.033</td>
<td>0.038</td>
</tr>
<tr>
<td>c</td>
<td></td>
<td>0.016</td>
<td>0.020</td>
<td>0.029</td>
<td>0.031</td>
<td>0.031</td>
<td>0.034</td>
<td>0.041</td>
<td>0.052</td>
<td>0.068</td>
</tr>
<tr>
<td>d</td>
<td></td>
<td>0.013</td>
<td>0.017</td>
<td>0.024</td>
<td>0.026</td>
<td>0.026</td>
<td>0.028</td>
<td>0.034</td>
<td>0.043</td>
<td>0.057</td>
</tr>
<tr>
<td>e</td>
<td></td>
<td>0.015</td>
<td>0.016</td>
<td>0.016</td>
<td>0.017</td>
<td>0.019</td>
<td>0.024</td>
<td>0.027</td>
<td>0.033</td>
<td>0.038</td>
</tr>
<tr>
<td>f</td>
<td></td>
<td>0.016</td>
<td>0.020</td>
<td>0.029</td>
<td>0.031</td>
<td>0.031</td>
<td>0.034</td>
<td>0.041</td>
<td>0.052</td>
<td>0.068</td>
</tr>
<tr>
<td>g</td>
<td></td>
<td>0.011</td>
<td>0.013</td>
<td>0.016</td>
<td>0.016</td>
<td>0.017</td>
<td>0.021</td>
<td>0.025</td>
<td>0.030</td>
<td>0.035</td>
</tr>
<tr>
<td>h</td>
<td></td>
<td>0.007</td>
<td>0.010</td>
<td>0.012</td>
<td>0.012</td>
<td>0.012</td>
<td>0.015</td>
<td>0.015</td>
<td>0.015</td>
<td>0.015</td>
</tr>
</tbody>
</table>

**Installation of the circular spline**

Conduct design and part control corresponding to the load condition for installation of the circular spline. Transmission torques by the recommended bolts and tightening torques are shown in the following table.

**Installation with bolts**

<table>
<thead>
<tr>
<th>Item</th>
<th>Size</th>
<th>14</th>
<th>20</th>
<th>25</th>
<th>32</th>
<th>40</th>
<th>50</th>
<th>65</th>
<th>80</th>
<th>100</th>
</tr>
</thead>
<tbody>
<tr>
<td>Number of bolts</td>
<td></td>
<td>6</td>
<td>6</td>
<td>6</td>
<td>6</td>
<td>6</td>
<td>6</td>
<td>6</td>
<td>8</td>
<td>8</td>
</tr>
<tr>
<td>Bolt size</td>
<td></td>
<td>M3</td>
<td>M3</td>
<td>M4</td>
<td>M5</td>
<td>M6</td>
<td>M8</td>
<td>M10</td>
<td>M10</td>
<td>M12</td>
</tr>
<tr>
<td>Pitch Circle</td>
<td>mm</td>
<td>44</td>
<td>60</td>
<td>75</td>
<td>100</td>
<td>120</td>
<td>150</td>
<td>195</td>
<td>240</td>
<td>290</td>
</tr>
<tr>
<td>Diameter</td>
<td></td>
<td>2.0</td>
<td>2.0</td>
<td>4.5</td>
<td>9.0</td>
<td>15.3</td>
<td>37</td>
<td>74</td>
<td>74</td>
<td>128</td>
</tr>
<tr>
<td>Clamp Torque</td>
<td>Nm</td>
<td>0.20</td>
<td>0.20</td>
<td>0.46</td>
<td>0.92</td>
<td>1.56</td>
<td>3.8</td>
<td>7.5</td>
<td>7.5</td>
<td>13.1</td>
</tr>
<tr>
<td>Torque Transmission</td>
<td>Nm</td>
<td>54</td>
<td>74</td>
<td>159</td>
<td>338</td>
<td>573</td>
<td>1300</td>
<td>2680</td>
<td>4410</td>
<td>7750</td>
</tr>
<tr>
<td></td>
<td>kgfm</td>
<td>5.5</td>
<td>7.5</td>
<td>16</td>
<td>34</td>
<td>58</td>
<td>132</td>
<td>273</td>
<td>450</td>
<td>790</td>
</tr>
</tbody>
</table>

*(Table 121-1/Notes)*

1. The material of the thread must withstand the clamp torque.
2. Recommended bolt: JIS B 1176 socket head cap screw / Strength range: JIS B 1051 over 12.9.
3. Torque coefficient: K=0.2
4. Clamp coefficient: A=1.4
5. Tightening friction coefficient μ=0.15
Precautions on assembly

Maintain the recommended tolerances shown in Figure 122-1 and Table 122-1 for optimal performance.

Lubrication

There are two types of lubrication: oil lubrication and grease lubrication. Although oil lubrication is common, grease lubrication is applicable to intermittent operation.

■ Oil lubrication

1. Types of Oil

The specified standard lubricant is industrial gear oil class-2 (extreme pressure) ISO VG68 (age 18).

2. Oil quantity

The recommended oil level is shown in Table 122-1.

<table>
<thead>
<tr>
<th>Size</th>
<th>14</th>
<th>20</th>
<th>25</th>
<th>32</th>
<th>40</th>
<th>50</th>
<th>65</th>
<th>80</th>
<th>100</th>
</tr>
</thead>
<tbody>
<tr>
<td>A</td>
<td>7</td>
<td>12</td>
<td>15</td>
<td>31</td>
<td>38</td>
<td>44</td>
<td>62</td>
<td>75</td>
<td>94</td>
</tr>
</tbody>
</table>

■ Grease lubrication

Different from oil lubrication, as a cooling effect is not expected from grease lubrication, it is only available for short operation.

- Operating condition: ED ≤ 10 or less, continuous operation for 10 minutes or less, the maximum allowable input rotational speed in Table 114-1 or less
- Recommended grease: Harmonic Grease S-1A for sizes 20 to 100
  - Harmonic Grease S-2 for size 14

(Note) If you use the product over ED or the maximum allowable rotational speed, the grease will deteriorate, will not work as a lubricating mechanism and will result in damaging the reducer earlier. Extreme care should be taken.
**Tooth profile**

- S tooth profile 009

**Rotational direction and reduction ratio**

- Cup style 010
- Silk hat style 010
- Pancake style 011

**Rating table definitions** 012

**Life** 012

**Torque limits** 013

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**Lubrication**

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**Torsional stiffness** 020

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**Vibration** 021

**Starting torque** 022

**Backdriving torque** 022

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**Design guidelines**

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- How to calculate the maximum moment load 030
- How to calculate the average load 031
- How to calculate the radial load coefficient (X) and axial load coefficient (Y) 031
- How to calculate life 032
- How to calculate the life under oscillating movement 033
- How to calculate the static safety coefficient 034

---

**Engineering Data**

Tooth profile

- S tooth profile

Rotational direction and reduction ratio

- Cup style
- Silk hat style
- Pancake style

Rating table definitions

Life

Torque limits

Product sizing and selection

Lubrication

- Grease lubricant
- Precautions on using Harmonic Grease® 4B No.2
- Oil lubricant
- Lubricant for special environments

Torsional stiffness

Positional accuracy

Vibration

Starting torque

Backdriving torque

No-load running torque

Efficiency

Design guidelines

- Design guideline
- Bearing support of the input and output shafts
- Wave Generator

Assembly guidelines

- Sealing
- Assembly Precautions
- “dedoidal” state

Checking output bearing

- Checking procedure
- How to calculate the maximum moment load
- How to calculate the average load
- How to calculate the radial load coefficient (X) and axial load coefficient (Y)
- How to calculate life
- How to calculate the life under oscillating movement
- How to calculate the static safety coefficient
Tooth Profile

S tooth profile

Harmonic Drive developed a unique gear tooth profile that optimizes the tooth engagement. It has a special curved surface unique to the S tooth profile that allows continuous contact with the tooth profile. It also alleviates the concentration of stress by widening the width of the tooth groove against the tooth thickness and enlarging the radius on the bottom. This tooth profile (the “S tooth”) enables up to 30% of the total number of teeth to be engaged simultaneously.

Additionally the large tooth root radius increases the tooth strength compared with an involute tooth. This technological innovation results in high torque, high torsional stiffness, long life and smooth rotation.

*Patented
Rotational direction and reduction ratio

**Cup Style**
Series: CSG, CSF, CSD, CSF-mini

**Rotational direction**

1. **Reducer**
   - Input: Wave Generator (WG)
   - Output: Flexspline (FS)
   - Fixed: Circular Spline (CS)
   - Reduction ratio: $i = \frac{1}{R}$

2. **Reducer**
   - Input: Wave Generator (WG)
   - Output: Flexspline (FS)
   - Fixed: Circular Spline (CS)
   - Reduction ratio: $i = \frac{R}{R+1}$

3. **Reducer**
   - Input: Flexspline (FS)
   - Output: Circular Spline (CS)
   - Fixed: Wave Generator (WG)
   - Reduction ratio: $i = \frac{R}{R+1}$

4. **Overdrive**
   - Input: Circular Spline (CS)
   - Output: Flexspline (FS)
   - Fixed: Wave Generator (WG)
   - Reduction ratio: $i = \frac{R+1}{R}$

5. **Overdrive**
   - Input: Flexspline (FS)
   - Output: Circular Spline (CS)
   - Fixed: Wave Generator (WG)
   - Reduction ratio: $i = \frac{R+1}{R}$

6. **Overdrive**
   - Input: Circular Spline (CS)
   - Output: Flexspline (FS)
   - Fixed: Wave Generator (WG)
   - Reduction ratio: $i = \frac{R+1}{R}$

7. **Differential**
   - When all of the wave generator, the flexspline and the circular spline rotate, Combinations (1) through (6) are available.

---

**Silk hat**
Series: SHG, SHF, SHD

**Rotational direction**

1. **Reducer**
   - Input: Wave Generator (WG)
   - Output: Flexspline (FS)
   - Fixed: Circular Spline (CS)
   - Reduction ratio: $i = \frac{1}{R}$

2. **Reducer**
   - Input: Wave Generator (WG)
   - Output: Flexspline (FS)
   - Fixed: Circular Spline (CS)
   - Reduction ratio: $i = \frac{R}{R+1}$

3. **Reducer**
   - Input: Flexspline (FS)
   - Output: Circular Spline (CS)
   - Fixed: Wave Generator (WG)
   - Reduction ratio: $i = \frac{R}{R+1}$

4. **Overdrive**
   - Input: Circular Spline (CS)
   - Output: Flexspline (FS)
   - Fixed: Wave Generator (WG)
   - Reduction ratio: $i = \frac{R+1}{R}$

5. **Overdrive**
   - Input: Flexspline (FS)
   - Output: Circular Spline (CS)
   - Fixed: Wave Generator (WG)
   - Reduction ratio: $i = \frac{R+1}{R}$

6. **Overdrive**
   - Input: Circular Spline (CS)
   - Output: Flexspline (FS)
   - Fixed: Wave Generator (WG)
   - Reduction ratio: $i = \frac{R+1}{R}$

7. **Differential**
   - When all of the wave generator, the flexspline and the circular spline rotate, Combinations (1) through (6) are available.
### Rotational direction

![Diagram of rotational direction](image)

(Note) Contact us if you use the product as Accelerator (5) and (6).

### Reduction ratio

The reduction ratio is determined by the number of teeth of the Flexspline and the Circular Spline

- **Input:** Wave Generator  
  **Output:** Circular Spline  
  **Fixed:** Wave Generator
  
  
  - **Reduction ratio:** \( i_1 = \frac{1}{R_1} = \frac{Z_f - Z_c}{Z_f} \)
  
  - **Example:**  
    - Number of teeth of the Flexspline: 200  
    - Number of teeth of the Circular Spline: 202

- **Input:** Wave Generator  
  **Output:** Flexspline  
  **Fixed:** Wave Generator
  
  
  - **Reduction ratio:** \( i_2 = \frac{1}{R_2} = \frac{Z_c - Z_f}{Z_c} \)

- **Input:** Wave Generator  
  **Output:** Flexspline  
  **Fixed:** Flexspline
  
  
  - **Reduction ratio:** \( i_3 = \frac{1}{R_3} = \frac{Z_f - Z_c}{Z_f} \)

**Ri** indicates the reduction ratio value from the ratings table.
Rating Table Definitions

See the corresponding pages of each series for values.

■ Rated torque
Rated torque indicates allowable continuous load torque at rated input speed.

■ Limit for Repeated Peak Torque
(see Graph 12-1)
During acceleration and deceleration the Harmonic Drive® gear experiences a peak torque as a result of the moment of inertia of the output load. The table indicates the limit for repeated peak torque.

■ Limit for Average Torque
In cases where load torque and input speed vary, it is necessary to calculate an average value of load torque. The table indicates the limit for average torque. The average torque calculated must not exceed this limit. (calculation formula: Page 14)

■ Limit for Momentary Peak Torque
(see Graph 12-1)
The gear may be subjected to momentary peak torques in the event of a collision or emergency stop. The magnitude and frequency of occurrence of such peak torques must be kept to a minimum and they should, under no circumstance, occur during normal operating cycle. The allowable number of occurrences of the momentary peak torque may be calculated by using formula 13-1.

■ Maximum Average Input Speed
Maximum Input Speed
Do not exceed the allowable rating. (calculation formula of the average input speed: Page 14).

■ Moment of Inertia
The rating indicates the moment of inertia reflected to the gear input.

Life

■ Life of the wave generator
The life of a gear is determined by the life of the wave generator bearing. The life may be calculated by using the input speed and the output load torque.

### Calculation formula for Rated Lifetime

\[
L_h = L_n \left( \frac{T_r}{T_{av}} \right) \left( \frac{N_r}{N_{av}} \right)
\]

### Life of the wave generator

<table>
<thead>
<tr>
<th>Series name</th>
<th>Life</th>
</tr>
</thead>
<tbody>
<tr>
<td>L_n</td>
<td>L10: 35,000 hours, L50: 7,000 hours</td>
</tr>
<tr>
<td>L_{av} (average life)</td>
<td>L10: 50,000 hours, L50: 10,000 hours</td>
</tr>
</tbody>
</table>

*Life is based on the input speed and output load torque from the rating table.*
Torque Limits

■ Strength of flexspline

The Flexspline is subjected to repeated deflections, and its strength determines the torque capacity of the Harmonic Drive® gear. The values given for Rated Torque at Rated Speed and for the allowable Repeated Peak Torque are based on an infinite fatigue life for the Flexspline. The torque that occurs during a collision must be below the momentary peak torque (impact torque). The maximum number of occurrences is given by the equation below.

\[ N = \frac{1.0 \times 10^4}{2 \times \frac{n}{60} \times t} \]

Allowable limit of the bending cycles of the flexspline during rotation of the wave generator while the impact torque is applied: \(1.0 \times 10^4\) (cycles)

The torque that occurs during a collision must be below the momentary peak torque (impact torque). The maximum number of occurrences is given by the equation below.

**Calculation formula**

<table>
<thead>
<tr>
<th>Allowable occurrences</th>
<th>(N) occurrences</th>
</tr>
</thead>
<tbody>
<tr>
<td>Time that impact torque is applied</td>
<td>(t) sec</td>
</tr>
<tr>
<td>Rotational speed of the wave generator</td>
<td>(n) rpm</td>
</tr>
</tbody>
</table>

The flexspline bends two times per one revolution of the wave generator.

If the number of occurrences is exceeded, the Flexspline may experience a fatigue failure.

■ Ratcheting torque

When excessive torque (8 to 9 times rated torque) is applied while the gear is in motion, the teeth between the Circular Spline and Flexspline may not engage properly. This phenomenon is called ratcheting and the torque at which this occurs is called ratcheting torque. Ratcheting may cause the Flexspline to become non-concentric with the Circular Spline. Operating in this condition may result in shortened life and a Flexspline fatigue failure.

\[ \text{Caution} \]

Once ratcheting occurs, the teeth wear excessively and the ratcheting torque may be lowered.

When ratcheting occurs, the teeth may not be correctly engaged and become out of alignment as shown in Figure 013-1. Operating the drive in this condition will cause vibration and damage the flexspline.

\[ \text{Caution} \]

When the flexspline buckles, early failure of the HarmonicDrive® gear will occur.

■ Buckling torque

When a highly excessive torque (16 to 17 times rated torque) is applied to the output with the input stationary, the flexspline may experience plastic deformation. This is defined as buckling torque.

\[ \text{Caution} \]

“There is “Dedoidal” condition.”

* See the corresponding pages of each series for buckling torque values.

* Ratcheting torque is affected by the stiffness of the housing to be used when installing the circular spline. Contact us for details of the ratcheting torque.
In general, a servo system rarely operates at a continuous load and speed. The input rotational speed, load torque change and comparatively large torque are applied at start and stop. Unexpected impact torque may be applied. These fluctuating load torques should be converted to the average load torque when selecting a model number. As an accurate cross roller bearing is built in the direct external load support (output flange), the maximum moment load, life of the cross roller bearing and the static safety coefficient should also be checked.

### Checking the application motion profile
Review the application motion profile. Check the specifications shown in the figure below.

![Graph](image_url)

**Obtain the value of each application motion profile.**
- **Load torque**  $T_1$ (Nm)
- **Time**  $t_1$ (sec)
- **Output rotational speed**  $n_1$ (rpm)

**Normal operation pattern**
- **Starting (acceleration)**  $T_1$, $t_1$, $n_1$
- **Steady operation**  $T_2$, $t_2$, $n_2$
- **Stopping (deceleration)**  $T_3$, $t_3$, $n_3$
- **Dwell**  $T_4$, $t_4$, $n_4$

**Maximum rotational speed**
- Max. output speed  $n_{max}$
- Max. input rotational speed  $n_{i max}$ (Restricted by motors)

**Emergency stop torque**
- When impact torque is applied  $T_s$, $t_s$, $n_s$

**Required life**  $L_{10} = L$ (hours)

### Flowchart for selecting a size
Please use the flowchart shown below for selecting a size. Operating conditions must not exceed the performance ratings.

1. **Calculate the average load torque applied on the output side from the application motion profile** $T_{av}$ (Nm).
   
   $T_{av} = \frac{3}{n_1} \sum_{i=1}^{n} T_i t_1 + T_{2} t_2 + \cdots + T_{n} t_n$

2. **Make a preliminary model selection with the following conditions.** $T_{av} \leq$ Limit for average torque for model number
   
   (See the rating table on Page 39.)

3. **Calculate the average output speed:**
   
   $n_{av} = \left(\frac{n_1 t_1 + n_2 t_2 + \cdots + n_n t_n}{t_1 + t_2 + \cdots + t_n}\right)$

4. **Obtain the reduction ratio** $R$.
   A limit is placed on “$n_{i max}$” by motors.

5. **Calculate the average input rotational speed** from the average output rotational speed ($n_{av}$) and the reduction ratio ($n_{i max}$).

6. **Calculate the maximum input rotational speed** from the max. output rotational speed ($n_{max}$) and the reduction ratio ($n_{i max}$).

7. **Check whether the preliminary model number satisfies the following condition from the rating table.**
   
   $n_{i max} \leq R \times n_{i max}$

8. **Check whether $T_1$ and $T_2$ are less than the repeated peak torque specification.**

9. **Check whether $T_3$ is less than the the momentary peak torque specification.**

10. **Calculate the allowable number of rotations during impact torque.**
    
    $N_s = \frac{10^4}{2 \times n_{i max} \times R \times t_1}$

11. **Calculate the lifetime.**
    
    $L_{10} = 7000 \left(\frac{T_{av}}{T_s} \right)^3 \frac{n_{i max}}{n_{i max}} (hours)$

12. **Check whether the calculated life is equal to or more than the life of the wave generator (see Page 13).**

The model number is confirmed.
### Example of model number selection

<table>
<thead>
<tr>
<th>Normal operation pattern</th>
<th>Value of each application motion profile</th>
<th>Maximum rotational speed</th>
<th>Required life</th>
</tr>
</thead>
<tbody>
<tr>
<td>Starting (acceleration)</td>
<td>Load torque: T1 = 400 Nm, t1 = 0.3 sec, n1 = 7 rpm</td>
<td>Max. output speed: no max = 14 rpm</td>
<td>L10 = 7000 (hours)</td>
</tr>
<tr>
<td>Steady operation</td>
<td>Time: t = (sec)</td>
<td>Max. input speed: ni max = 1800 rpm</td>
<td></td>
</tr>
<tr>
<td>(constant velocity)</td>
<td>Output speed: n = (rpm)</td>
<td>(Restricted by motors)</td>
<td></td>
</tr>
<tr>
<td>Stopping (deceleration)</td>
<td></td>
<td>Emergency stop torque: Ts = 500 Nm, ts = 0.15 sec, ns = 14 rpm</td>
<td></td>
</tr>
<tr>
<td>Dwell</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

#### Normal operation pattern

- **Load torque:**
  - T1 = 400 Nm, t1 = 0.3 sec, n1 = 7 rpm
  - T2 = 320 Nm, t2 = 3 sec, n2 = 14 rpm
  - T3 = 200 Nm, t3 = 0.4 sec, n3 = 7 rpm
  - T4 = 0 Nm, t4 = 0.2 sec, n4 = 0 rpm

- **Time:**
  - T2 = 320 Nm, t2 = 3 sec, n2 = 14 rpm
  - T3 = 200 Nm, t3 = 0.4 sec, n3 = 7 rpm

- **Output speed:**
  - T4 = 0 Nm, t4 = 0.2 sec, n4 = 0 rpm

#### Calculation of average load torque

Calculate the average load torque to the output side based on the application motion profile: $T_{av}$ (Nm).

$$T_{av} = 3 \times \frac{7 \text{ rpm} \times 0.3 \text{ sec} \times [400 \text{ Nm}]^2 + 14 \text{ rpm} \times 3 \text{ sec} \times [320 \text{ Nm}]^2 + 7 \text{ rpm} \times 0.4 \text{ sec} \times [200 \text{ Nm}]^2}{7 \text{ rpm} \times 0.3 \text{ sec} \times 14 \text{ rpm} \times 3 \text{ sec} + 7 \text{ rpm} \times 0.4 \text{ sec} \times 4 \text{ sec}}$$

#### Calculation of output rotational speed

Calculate the maximum input rotational speed from the maximum output rotational speed (no max) and the reduction ratio (R): $n_i = \frac{n_o}{\text{R}}$

- **Maximum output rotational speed:**
  - $n_o = 620 \text{ rpm}$
  - $n_o = 319 \text{ rpm}$

- **Required speed:**
  - $n_i = 14 \text{ rpm}$
  - $n_i = 14 \text{ rpm}$

#### Check whether the preliminary selected model number satisfies the following condition from the rating table.

- **Ni av:**
  - 1440 rpm
  - 3600 rpm

- **Ni max:**
  - 1680 rpm
  - 5660 rpm

#### Check whether T1 and T3 are equal to or less than the repeated peak torque specification.

- **T1:**
  - 400 Nm ≤ 617 Nm (Limit of repeated peak torque of size 40)

- **T3:**
  - 200 Nm ≤ 617 Nm (Limit of repeated peak torque of size 40)

#### Check whether T5 is equal to or less than the momentary peak torque specification.

- **T5:**
  - 500 Nm ≤ 1180 Nm (Limit for momentary torque of size 40)

#### Calculate the allowable number ($N_9$) rotation during impact torque and confirm $\leq 1.0 \times 10^4$

$$N_9 = \frac{1.0 \times 10^4}{2 \times \frac{14 \text{ rpm}}{120} \times \frac{1800 \text{ rpm}}{60} 	imes 0.15 \text{ sec}} = 1190 \leq 1.0 \times 10^4$$

#### Calculate the lifetime.

$$L_{10} = \frac{294 \text{ Nm}}{2} \times \frac{319 \text{ Nm}}{1} \times \frac{2000 \text{ rpm}}{1440 \text{ rpm}} = 7000 \text{ (hours)}$$

#### Review the operation conditions, size and reduction ratio.

- **L10:**
  - 7000 (hours)

The selection of model number CSF-40-120-2A-GR is confirmed from the above calculations.
Lubrication

Component Sets: CSD-2A, CSF-2A, CSG-2A, FB-2, FB-0, FR-2, SHF-2A, SHG-2A and SHD and SHG/SHF -2SO and -2SH gear units: Grease lubricant and oil lubricant are available for lubricating the component sets and SHD gear unit. It is extremely important to properly grease your component sets and SHD gear unit. Proper lubrication is essential for high performance and reliability. Harmonic Drive® component sets are shipped with a rust- preventative oil. The characteristics of the lubricating grease and oil types approved by Harmonic Drive are not changed by mixing with the preservation oil. It is therefore not necessary to remove the preservation oil completely from the gear components. However, the mating surfaces must be degreased before the assembly.

Gear Units: CSG/CSF 2UH and 2UH-LW; CSD-2UF and -2UH; SHG/SHF-2UH and 2UH-LW; SHG/SHF-2UJ; CSF Supermini, CSF Mini, and CSF-2UP.

Grease lubricant is standard for lubricating the gear units. You do not need to apply grease during assembly as the product is lubricated and shipped. See Page 19 for using lubricant beyond the temperature range in table 16-2.

* Contact us if you want consistency zero (NLGI No.0) for maintenance reasons.

### Grease lubricant

#### Types of lubricant

**Harmonic Grease® SK-1A**

This grease was developed for Harmonic Drive® gears and features good durability and efficiency.

**Harmonic Grease® SK-2**

This grease was developed for small sized Harmonic Drive® gears and features smooth rotation of the Wave Generator since high pressure additive is liquefied.

**Harmonic Grease® 4B No.2**

This has been developed exclusively for the CSF and CSG and features long life and can be used over a wide range of temperature.

(Note) 1. Grease lubrication must have proper sealing, this is essential for 4B No.2.

   Rotating part: Oil seal with spring is needed.

   Mating part: O ring or seal adhesive is needed.

2. The grease has the highest deterioration rate in the region where the grease is subjected to the greatest shear (near wave generator). Its viscosity is between JIS No.5 and No.00 depending on the operation.

### Grease specification

<table>
<thead>
<tr>
<th>Grease</th>
<th>SK-1A</th>
<th>SK-2</th>
<th>4B No.2</th>
</tr>
</thead>
<tbody>
<tr>
<td>Base oil</td>
<td>Refined oil</td>
<td>Refined oil</td>
<td>Composite hydrocarbon oil</td>
</tr>
<tr>
<td>Base Viscosity cSt (25°C)</td>
<td>265 to 295</td>
<td>265 to 295</td>
<td>290 to 320</td>
</tr>
<tr>
<td>Thickening agent</td>
<td>Lithium soap base</td>
<td>Lithium soap base</td>
<td>Urea</td>
</tr>
<tr>
<td>NLGI consistency No.</td>
<td>No. 2</td>
<td>No. 2</td>
<td>No. 1.5</td>
</tr>
<tr>
<td>Additive</td>
<td>Extreme-pressure additive, others</td>
<td>Extreme-pressure additive, others</td>
<td>Extreme-pressure additive, others</td>
</tr>
<tr>
<td>Drop Point</td>
<td>197°C</td>
<td>198°C</td>
<td>247°C</td>
</tr>
<tr>
<td>Appearance</td>
<td>Yellow</td>
<td>Green</td>
<td>Light yellow</td>
</tr>
<tr>
<td>Storage life</td>
<td>5 years in sealed condition</td>
<td>5 years in sealed condition</td>
<td>5 years in sealed condition</td>
</tr>
</tbody>
</table>

### Grease characteristics

<table>
<thead>
<tr>
<th>Grease</th>
<th>SK-1A</th>
<th>SK-2</th>
<th>4B No.2</th>
</tr>
</thead>
<tbody>
<tr>
<td>Durability</td>
<td>☐</td>
<td>☐</td>
<td>☐</td>
</tr>
<tr>
<td>Fretting resistance</td>
<td>☐</td>
<td>☐</td>
<td>☐</td>
</tr>
<tr>
<td>Low-temperature performance</td>
<td>☐</td>
<td>☐</td>
<td>☐</td>
</tr>
<tr>
<td>Grease leakage</td>
<td>☐</td>
<td>☐</td>
<td>☐</td>
</tr>
</tbody>
</table>

* Excellent ☀
  Good ☐
  Use Caution ☐

### Name of lubricant

<table>
<thead>
<tr>
<th>Grease</th>
<th>Table 016-1</th>
</tr>
</thead>
<tbody>
<tr>
<td>Harmonic Grease® SK-1A</td>
<td></td>
</tr>
<tr>
<td>Harmonic Grease® SK-2</td>
<td></td>
</tr>
<tr>
<td>Harmonic Grease® 4B No.2</td>
<td></td>
</tr>
</tbody>
</table>

### Temperature

<table>
<thead>
<tr>
<th>Grease</th>
<th>Table 016-2</th>
</tr>
</thead>
<tbody>
<tr>
<td>SK-1A 0°C to +40°C</td>
<td></td>
</tr>
<tr>
<td>SK-2 0°C to +40°C</td>
<td></td>
</tr>
<tr>
<td>4B No.2 -10°C to +70°C</td>
<td></td>
</tr>
<tr>
<td>Oil ISO VG88 0°C to +40°C</td>
<td></td>
</tr>
</tbody>
</table>

* The hottest section should not be more than 40° above the ambient temperature.

Note: The three basic components of the gear - the Flexspline, Wave Generator and Circular Spline - are matched and serialized in the factory. Depending on the product they are either greased or prepared with preservation oil. Then the individual components are assembled. If you receive several units, please be careful not to mix the matched components. This can be avoided by verifying that the serial numbers of the assembled gear components are identical.

### Compatible grease by size

Compatible grease varies depending on the size and reduction ratio. See the following compatibility table. We recommend SK-1A and SK-2 for general use.

#### Ratios 30:1

<table>
<thead>
<tr>
<th>Size</th>
<th>8</th>
<th>11</th>
<th>14</th>
<th>17</th>
<th>20</th>
<th>25</th>
<th>32</th>
</tr>
</thead>
<tbody>
<tr>
<td>SK-1A</td>
<td>☐</td>
<td>☐</td>
<td>☐</td>
<td>☐</td>
<td>☐</td>
<td>☐</td>
<td>☐</td>
</tr>
<tr>
<td>SK-2</td>
<td>☐</td>
<td>☐</td>
<td>☐</td>
<td>☐</td>
<td>☐</td>
<td>☐</td>
<td>☐</td>
</tr>
<tr>
<td>4B No.2</td>
<td>☐</td>
<td>☐</td>
<td>☐</td>
<td>☐</td>
<td>☐</td>
<td>☐</td>
<td>☐</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Size</th>
<th>40</th>
<th>45</th>
<th>50</th>
<th>58</th>
<th>65</th>
<th>80</th>
<th>90</th>
<th>100</th>
</tr>
</thead>
<tbody>
<tr>
<td>SK-1A</td>
<td>☐</td>
<td>☐</td>
<td>☐</td>
<td>☐</td>
<td>☐</td>
<td>☐</td>
<td>☐</td>
<td>☐</td>
</tr>
<tr>
<td>SK-2</td>
<td>☐</td>
<td>☐</td>
<td>☐</td>
<td>☐</td>
<td>☐</td>
<td>☐</td>
<td>☐</td>
<td>☐</td>
</tr>
<tr>
<td>4B No.2</td>
<td>☐</td>
<td>☐</td>
<td>☐</td>
<td>☐</td>
<td>☐</td>
<td>☐</td>
<td>☐</td>
<td>☐</td>
</tr>
</tbody>
</table>

* Standard grease ☐
  Semi-standard grease ☐
  Recommended grease for long life and high load ☐

* Oil lubrication is required for component-sets size 50 or larger with a reduction ratio of 50:1.
When to replace grease

The wear characteristics of the gear are strongly influenced by the condition of the grease lubrication. The condition of the grease is affected by the ambient temperature. The graph 017-1 shows the maximum number of input rotations for various temperatures. This graph applies to applications where the average load torque does not exceed the rated torque.

Note: Recommended Grease: SK-1A or SK-2

When to replace grease: LGTn (when the average load torque is equal to or less than the rated torque)

Graph 017-1

![Graph showing the relationship between grease life, number of input rotations, and grease temperature.]

Calculation formula when the average load torque exceeds the rated torque

Formula 017-1

\[ L_{\text{avg}} = L_{\text{min}} \times \left( \frac{Tr}{Tav} \right)^3 \]

Other precautions

1. Avoid mixing different kinds of grease. The gear should be in an individual case when installed.

2. Please contact us when you use HarmonicDrive\textsuperscript{®} gears at constant load or in one direction continuously, as it may cause lubrication problems.

3. Grease leakage. A sealed structure is needed to maintain the high durability of the gear and prevent grease leakage.

See the corresponding pages of the design guide of each series for “Recommended minimum housing clearance,” Application guide” and “Application quantity.”
We recommend the following brands as a commercial lubricant.
The specified standard lubricant is “Industrial gear oil class-2 (extreme pressure) ISO VG68.”

Operation range for aging: Keep the output rotational angle as large as possible.
• Input rotational speed should be 1000rpm to 3000rpm. However, the lower rotational speed of 1000rpm is more effective.
• Set the speed as low as possible within the indicated range.
• The time required for aging is 20 minutes or longer.
• Operation range for aging: Keep the output rotational angle as large as possible.

Contact us if you have any questions for handling Harmonic Grease 4B No.2 lubrication.

Note: Strict sealing is required to prevent grease leakage.

Oil lubricant

Types of oil
The specified standard lubricant is “Industrial gear oil class-2 (extreme pressure) ISO VG68.”
We recommend the following brands as a commercial lubricant.

<table>
<thead>
<tr>
<th>Standard</th>
<th>Mobil Oil</th>
<th>Exxon</th>
<th>Shell</th>
<th>COSMO Oil</th>
<th>Japan Energy</th>
<th>NIPPON Oil</th>
<th>Idemitsu Kosan</th>
<th>General Oil</th>
<th>Klüber</th>
</tr>
</thead>
<tbody>
<tr>
<td>Industrial gear oil class-2</td>
<td>Mobilgear 600XP68</td>
<td>Spartan EP68</td>
<td>Omaia Oil 68</td>
<td>Cosmo gear SE68</td>
<td>ES gear G68</td>
<td>Bonock M68, Bonock AX68</td>
<td>Daphne super gear LW68</td>
<td>General Oil SP gear roll 68</td>
<td>Syntheso D-68EP</td>
</tr>
</tbody>
</table>

When to replace oil
First time ....................... 100 hours after starting operation
Second time or after .......... Every 1000 operation hours or every 6 months
Note that you should replace the oil earlier than specified if the operating condition is demanding.

Other precautions
1. Avoid mixing different kinds of oil. The gear should be in an individual case when installed.
2. When you use size 50 or above at max allowable input speed, please contact us as it may cause lubrication problems.

* Oil lubrication is required for component-sets size 50 or larger with a reduction ratio of 50:1.
Lubricant for special environments

When the ambient temperature is special (other than the "temperature range of the operating environment" on Page 016-2), you should select a lubricant appropriate for the operating temperature range.

<table>
<thead>
<tr>
<th>Type of lubricant</th>
<th>Operating temperature range</th>
<th>Available temperature range</th>
</tr>
</thead>
<tbody>
<tr>
<td>Grease</td>
<td>–10°C to + 11°C</td>
<td>–50°C to + 130°C</td>
</tr>
</tbody>
</table>

Harmonic Grease 4B No.2  

Harmonic Grease 4B No.2

The operating temperature range of Harmonic Grease 4B No.2 lubrication is the temperature at the lubricating section with the performance and characteristics of the gear taken into consideration. (It is not ambient temperature.)

As the available temperature range indicates the temperature of the independent lubricant, restriction is added on operating conditions (such as load torque, rotational speed and operating cycle) of the gear. When the ambient temperature is very high or low, materials of the parts of the gear need to be reviewed for suitability. Contact us if operating in high temperature.

Harmonic Grease 4B No.2 can be used in the available temperature range shown in Table 019-1. However, input running torque will increase at low temperatures, and grease life will be decreased at high temperatures due to oxidation and lubricant degradation.

### High temperature lubricant

<table>
<thead>
<tr>
<th>Type of lubricant</th>
<th>Lubricant and manufacturer</th>
<th>Available temperature range</th>
</tr>
</thead>
<tbody>
<tr>
<td>Grease</td>
<td>Mobil grease 28: Mobil Oil</td>
<td>–5°C to + 160°C</td>
</tr>
<tr>
<td>Oil</td>
<td>Mobil SHC-626: Mobil Oil</td>
<td>–5°C to + 140°C</td>
</tr>
</tbody>
</table>

### Low temperature lubricant

<table>
<thead>
<tr>
<th>Type of lubricant</th>
<th>Lubricant and manufacturer</th>
<th>Available temperature range</th>
</tr>
</thead>
<tbody>
<tr>
<td>Grease</td>
<td>Multemp SH-KII: Kyodo Oil</td>
<td>–30°C to + 60°C</td>
</tr>
<tr>
<td></td>
<td>Isoflex LDS-18 special A: KLÜBER</td>
<td>–25°C to + 80°C</td>
</tr>
<tr>
<td>Oil</td>
<td>SH-200-100CS: Toray Silicon</td>
<td>–40°C to + 140°C</td>
</tr>
<tr>
<td></td>
<td>Syntheso D-32EP: KLÜBER</td>
<td>–25°C to + 90°C</td>
</tr>
</tbody>
</table>
Torsional Stiffness

Stiffness and backlash of the drive system greatly affects the performance of the servo system. Please perform a detailed review of these items before designing your equipment and selecting a model number.

- **Stiffness**
  Fixing the input side (wave generator) and applying torque to the output side (flexspline) generates torsion almost proportional to the torque on the output side. Figure 018-1 shows the torsional angle at the output side when the torque applied on the output side starts from zero, increases up to +T0 and decreases down to −T0. This is called the “Torque – torsion angle diagram,” which normally draws a loop of 0 → A → B → A′ → B′ → A. The slope described in the “Torque – torsion angle diagram” is represented as the spring constant for the stiffness of the HarmonicDrive® gear (unit: Nm/rad).
  
  As shown in Figure 020-1, this “Torque – torsional angle diagram” is divided into 3 regions, and the spring constants in the area are represented by K1, K2 and K3.

- **Example for calculating the torsion angle**
  The torsion angle (θ) is calculated here using CSF-25-100-2A-GR as an example.

  When the applied torque is T1 or less, the torsion angle θ₁ is calculated as follows:
  
  When the load torque T₀ = 2.9 Nm
  
  \[
  \theta_1 = \frac{T_1}{K_1} = \frac{2.9}{3.1 \times 10^4} = 9.4 \times 10^{-4} \text{ rad} \quad (0.33 \text{ arc min})
  \]

  When the applied torque is between T1 and T2, the torsion angle θ₂ is calculated as follows:

  When the load torque is T₀ = 39 Nm
  
  \[
  \theta_2 = \theta_1 + \frac{(T_2 - T_0)}{K_2} = 4.4 \times 10^{-4} + \frac{(39 - 14)}{5.0 \times 10^4} = 1.5 \times 10^{-4} \text{ rad} \quad (0.2 \text{ arc sec})
  \]

  When a bidirectional load is applied, the total torsion angle will be 2x θ₂ plus hysteresis loss.

  * The torsion angle calculation is for the gear component set only and does not include any torsional windup of the output shaft.

  **Note:** See p.120 for torsional stiffness for pancake gearing.

- **Hysteresis loss (Silk hat and cup style only)**
  As shown in Figure 020-1, when the applied torque is increased to the rated torque and is brought back to zero, the torsional angle does not return exactly back to the zero point. This small difference (B – B’) is called hysteresis loss.

  - See the corresponding pages of each series for the hysteresis loss value.

- **Backlash (Silk hat and cup style only)**
  Hysteresis loss is primarily caused by internal friction. It is a very small value and will vary roughly in proportion to the applied load. Because HarmonicDrive® gears have zero backlash, the only true backlash is due to the clearance in the Oldham coupling, a self-aligning mechanism used on the wave generator. Since the Oldham coupling is used on the input, the backlash measured at the output is extremely small (arc-seconds) since it is divided by the gear reduction ratio.

  **Graph 021-1**

  **Spring constant diagram**

  **Formula variables**

  - \( f \): Frequency of the system
  - \( J \): Actual output angle
  - \( \theta \): Theoretical angle
  - \( \theta_{er} \): Transmission accuracy
  - \( N \): Gear speed
  - \( \theta_{er} = \frac{\theta - \theta_{er}}{2\pi} \cdot 100 \%
  - \( f = \frac{2\pi \cdot J}{2\pi} \)
  - \( J = \frac{\theta_{er} - \theta}{2\pi} \)
  - \( f = \frac{N}{\theta} \)
  - \( \theta_{er} = \frac{\theta}{2\pi} \cdot 100 \%
  - \( \theta = \frac{\theta_{er}}{2\pi} \)
  - \( J = \frac{\theta_{er}}{2\pi} \)
  - \( f = \frac{N}{\theta} \)
  - \( \theta_{er} = \frac{\theta}{2\pi} \cdot 100 \%
  - \( \theta = \frac{\theta_{er}}{2\pi} \)
  - \( J = \frac{\theta_{er}}{2\pi} \)
  - \( f = \frac{N}{\theta} \)
  - \( \theta_{er} = \frac{\theta}{2\pi} \cdot 100 \%
  - \( \theta = \frac{\theta_{er}}{2\pi} \)
  - \( J = \frac{\theta_{er}}{2\pi} \)
  - \( f = \frac{N}{\theta} \)
  - \( \theta_{er} = \frac{\theta}{2\pi} \cdot 100 \%
  - \( \theta = \frac{\theta_{er}}{2\pi} \)
  - \( J = \frac{\theta_{er}}{2\pi} \)
  - \( f = \frac{N}{\theta} \)
  - \( \theta_{er} = \frac{\theta}{2\pi} \cdot 100 \%
  - \( \theta = \frac{\theta_{er}}{2\pi} \)
  - \( J = \frac{\theta_{er}}{2\pi} \)
  - \( f = \frac{N}{\theta} \)
  - \( \theta_{er} = \frac{\theta}{2\pi} \cdot 100 \%
  - \( \theta = \frac{\theta_{er}}{2\pi} \)
  - \( J = \frac{\theta_{er}}{2\pi} \)
  - \( f = \frac{N}{\theta} \)
  - \( \theta_{er} = \frac{\theta}{2\pi} \cdot 100 \%
  - \( \theta = \frac{\theta_{er}}{2\pi} \)
Positional Accuracy

Positional Accuracy values represent the difference between the theoretical angle and the actual angle of output for any given input. The values shown in the table are maximum values.

- See the corresponding pages of each series for transmission accuracy values.

| θ <sub>er</sub> | Transmission accuracy |
| θ <sub>1</sub> | Input angle |
| θ <sub>2</sub> | Actual output angle |
| R | Reduction ratio |

Example of measurement

Figure 021-1

\[ θ_{er} = |θ_2 - \frac{θ_1}{R}| \]

Vibration

The primary frequency of the transmission error of the HarmonicDrive® gear may cause a vibration of the load inertia. This can occur when the driving frequency of the servo system including the HarmonicDrive® gear is at, or close to the resonant frequency of the system. Refer to the design guide of each series.

The primary component of the transmission error occurs twice per input revolution of the input. Therefore, the frequency generated by the transmission error is 2x the input frequency (rev/sec).

If the resonant frequency of the entire system, including the HarmonicDrive® gear, is F=15 Hz, then the input speed (N) which would generate that frequency could be calculated with the formula below.

\[ N = \frac{15}{2} \times 60 = 450 \text{ rpm} \]

The resonant frequency is generated at an input speed of 450 rpm.
Starting Torque

Starting torque is the torque value applied to the input side at which the output first starts to rotate. The values in the table of each series indicate the maximum value, and the lower-limit value indicates approximately \(\frac{1}{2}\) to \(\frac{1}{3}\) of the maximum value.

**Measurement conditions:**
- No-load, ambient temperature: +20°C

- See the corresponding pages of each series for starting torque values.

* Use the values in the table of each series as reference values as they vary depending on the usage conditions.

Backdriving Torque

Backdriving torque is the torque value applied to the output side at which the input first starts to rotate. The values in the table are maximum values, typical values are approximately \(\frac{1}{2}\) of the maximum values.

Note: Never rely on these values as a margin in a system that must hold an external load. A brake must be used where backdriving is not permissible.

**Measurement conditions:**
- No-load, ambient temperature: +20°C

- See the corresponding pages of each series for backdriving torque values.

* Use the values in the table of each series as reference values as they vary depending on the usage conditions.
No-Load Running Torque

No-load running torque is the torque which is required to rotate the input side (high speed side), when there is no load on the output side (low speed side). The graph of the no-load running torque shown in this catalog depends on the measurement conditions shown in Table 023-1. Add the compensation values shown by each series to all reduction ratios except 100:1.

- See the corresponding pages of each series for no-load running torque values.

Efficiency

The efficiency varies depending on the following conditions.
- Reduction ratio
- Input speed
- Load torque
- Temperature
- Lubrication (type and quantity)
The efficiency characteristics of each series shown in this catalog depends on the measurement condition shown in Table 023-2.

- See the corresponding pages of each series for efficiency values.

**Efficiency compensation coefficient**

If load torque is below rated torque, a compensation factor must be employed. Calculate the compensation coefficient Ke from the efficiency compensation coefficient graph of each series and use the following example for calculation.

**Example of calculation**

Efficiency $\eta$ (%) under the following condition is obtained from the example of CSF-20-80-2A-GR.
- Input rotational speed: 1000 rpm
- Load torque: 19.6 Nm
- Lubrication method: Grease lubrication (Harmonic Grease SK-1A)
- Lubricant temperature: 20°C
Since the rated torque of size 20 with a reduction ratio of 80 is 34 Nm (Ratings: Page 039), the torque ratio $\alpha$ is 0.58. ($\alpha=19.6/34=0.58$)

- The efficiency compensation coefficient is $Ke=0.93$ from Graph 023-1.
- Efficiency $\eta$ at load torque 19.6 Nm: $\eta=Ke\cdot\eta_R=0.93 \times 78=73\%$
Design Guidelines

Design guideline

The relative perpendicularity and concentricity of the three basic Harmonic Drive® elements have an important influence on accuracy and service life.

Misalignments will adversely affect performance and reliability. Compliance with recommended assembly tolerances is essential in order for the advantages of Harmonic Drive® gearing to be fully realized. Please consider the following when designing:

(1) Input shaft, Circular Spline and housing must be concentric.

(2) When operating, an axial force is generated on the wave generator. Input bearings must be selected to accommodate this axial load. See page 27.

(3) Even though a HarmonicDrive® gear is compact, it transmits large torques. Therefore, assure that all required bolts are used to fastened the circular spline and flexspline and that they are tightened to the recommended torque.

(4) As the flexspline is subject to elastic deformation, the A minimal clearance between the flexspline and housing is required. Refer to “Minimum Housing Clearance” on the drawing dimension tables.

(5) The input shaft and output shaft are supported by anti-friction bearings. As the wave generator and flexspline elements are meant to transmit pure torque only, the bearing arrangement needs to isolate the harmonic gearing from external forces applied to either shaft. A common bearing arrangement is depicted in the diagram.

(6) A clamping plate is recommended (item 6). Its purpose is to spread fastening forces and to avoid any chance of making physical contact with the thin section of the flexspline diaphragm. The clamping plate shall not exceed the diaphragm’s boss diameter and is to be designed in accordance with catalog recommendations.

Fig. 024-1

For the component sets, both input and output shafts must be supported by two adequately spaced bearings in order to withstand external radial and axial forces without excessive deflection.

In order to avoid damage to the component set when limited external loads are anticipated, both input and output shafts must be axially fixed.

Bearings must be selected whose radial play does not exceed ISO-standard C 2 class or “normal” class. The bearings should be axially and radially preloaded to eliminate backlash. Examples of correct bearing arrangements are shown in fig 025-1.

Bearing support for the input and output shafts

Fig. 025-1

Output Input

Input Output

Input

Output

Input

Input

Output

Motor

Input

Output
**Bearing support for the input and output shafts**

For the component sets, both input and output shafts must be supported by two adequately spaced bearings in order to withstand external radial and axial forces without excessive deflection. In order to avoid damage to the component set when limited external loads are anticipated, both input and output shafts must be axially fixed. Bearings must be selected whose radial play does not exceed ISO-standard C 2 class or "normal" class. The bearings should be axially and radially preloaded to eliminate backlash. Examples of correct bearing arrangements are shown in fig 025-1.
Wave generator

Structure of the wave generator

The wave generator includes an Oldham’s coupling type with a self-aligning structure and an integrated solid wave generator without a self-aligning structure, and which is used depends on the series.

See the diagram of each series for details. The basic structure of the wave generator and the shape are shown below.

![Diagram of wave generator components](image1)

- **Oldham’s coupling**
- **Solid wave generator**

![Diagram of Oldham’s coupling structure](image2)

- **Ball Separator**
- **Wave generator bearing**
- **Wave generator plug**
- **Insert**
- **Rubwasher**
- **Snap ring**
- **Wave generator hub**
Maximum hole diameter of wave generator

The standard hole dimension of the wave generator is shown for each size. The dimension can be changed within a range up to the maximum hole dimension. We recommend the dimension of keyway based on JIS standard. It is necessary that the dimension of keyways should sustain the transmission torque. * Tapered holes are also available.

In cases where a larger hole is required, use the wave generator without the Oldham coupling. The maximum diameter of the hole should be considered to prevent deformation of the Wave Generator plug by load torque. The dimension is shown in the table below and includes the dimension of depth of keyway. (This is the value including the dimension of the depth of keyway.)

<p>| Hole diameter of the wave generator hub with Oldham coupling | Table 027-1 Unit: mm |</p>
<table>
<thead>
<tr>
<th>Size</th>
<th>8</th>
<th>11</th>
<th>14</th>
<th>17</th>
<th>20</th>
<th>25</th>
<th>32</th>
<th>40</th>
<th>45</th>
<th>50</th>
<th>58</th>
<th>65</th>
<th>80</th>
<th>90</th>
<th>100</th>
</tr>
</thead>
<tbody>
<tr>
<td>Standard dim. (H7)</td>
<td>3</td>
<td>5</td>
<td>6</td>
<td>8</td>
<td>9</td>
<td>11</td>
<td>14</td>
<td>14</td>
<td>19</td>
<td>19</td>
<td>22</td>
<td>24</td>
<td>28</td>
<td>28</td>
<td>28</td>
</tr>
<tr>
<td>Minimum hole dim.</td>
<td>—</td>
<td>—</td>
<td>3</td>
<td>4</td>
<td>5</td>
<td>6</td>
<td>6</td>
<td>10</td>
<td>10</td>
<td>10</td>
<td>13</td>
<td>16</td>
<td>16</td>
<td>19</td>
<td>22</td>
</tr>
<tr>
<td>Maximum hole dim.</td>
<td>—</td>
<td>—</td>
<td>8</td>
<td>10</td>
<td>13</td>
<td>15</td>
<td>15</td>
<td>20</td>
<td>20</td>
<td>20</td>
<td>25</td>
<td>30</td>
<td>35</td>
<td>37</td>
<td>40</td>
</tr>
</tbody>
</table>

<p>| Maximum hole diameter without Oldham Coupling | Table 027-2 Unit: mm |</p>
<table>
<thead>
<tr>
<th>Size</th>
<th>8</th>
<th>11</th>
<th>14</th>
<th>17</th>
<th>20</th>
<th>25</th>
<th>32</th>
<th>40</th>
<th>45</th>
<th>50</th>
<th>58</th>
<th>65</th>
<th>80</th>
<th>90</th>
<th>100</th>
</tr>
</thead>
<tbody>
<tr>
<td>Max. hole dia. (V'φ)</td>
<td>10</td>
<td>14</td>
<td>17</td>
<td>20</td>
<td>23</td>
<td>28</td>
<td>36</td>
<td>42</td>
<td>47</td>
<td>52</td>
<td>60</td>
<td>67</td>
<td>72</td>
<td>84</td>
<td>95</td>
</tr>
<tr>
<td>Min. plug thick (H)</td>
<td>5.7</td>
<td>6.7</td>
<td>7.2</td>
<td>7.6</td>
<td>11.3</td>
<td>11.3</td>
<td>13.7</td>
<td>15.9</td>
<td>17.8</td>
<td>19</td>
<td>21.4</td>
<td>23.5</td>
<td>28.5</td>
<td>31.3</td>
<td>34.9</td>
</tr>
</tbody>
</table>

Axial Force of Wave Generator

When the gear is used to accelerate a load, the deflection of the Flexspline leads to an axial force acting on the Wave Generator. This axial force, which acts in the direction of the closed end of the Flexspline, must be supported by the bearings of the input shaft (motor shaft). When the gear is used to decelerate a load, an axial force acts to push the Wave Generator out of the Flexspline cup. Maximum axial force of the Wave Generator can be calculated by the equation shown below. The axial force may vary depending on its operating condition. The value of axial force tends to be a larger number when using high torque, extreme low speed and constant operation. The force is calculated (approximately) by the equation. In all cases, the Wave Generator must be axially (in both directions), as well as torsionally, fixed to the input shaft.

(Note)
Please contact us for further information on attaching the Wave Generator to the input (motor) shaft.

Formula for Axial Force  

Calculation example

Model name: CSF series
Size: 32
Reduction ratio: 50
Output torque: 382 Nm
(maximum allowable momentary torque)

\[
F = \frac{382}{(32 \times 0.00254)} \times 0.07 \times \tan 30°
\]

\[
F = 380 N
\]

<table>
<thead>
<tr>
<th>Formula for Axial Force</th>
<th>Table 027-3</th>
</tr>
</thead>
<tbody>
<tr>
<td>Reduction ratio</td>
<td>Calculation formula</td>
</tr>
<tr>
<td>30</td>
<td>( F = 2 \times 32 \times 0.07 \times \tan 30° )</td>
</tr>
<tr>
<td>50</td>
<td>( F = 2 \times 32 \times 0.07 \times \tan 30° )</td>
</tr>
<tr>
<td>80 or more</td>
<td>( F = 2 \times 50 \times 0.07 \times \tan 20° )</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Symbols for Formula</th>
<th>Table 027-4</th>
</tr>
</thead>
<tbody>
<tr>
<td>F</td>
<td>Axial force</td>
</tr>
<tr>
<td>D</td>
<td>Size</td>
</tr>
<tr>
<td>T</td>
<td>Output torque</td>
</tr>
</tbody>
</table>
Assembly Precautions

Sealing

Sealing is needed to maintain the high durability of the gear and prevent grease leakage. Recommended for all mating surfaces, if the o-ring is not used. Flanges provided with o-ring grooves must be sealed when a proper seal cannot be achieved using the o-ring alone.

- Rotating Parts .......................... Oil seal with spring is needed.
- Mating flange ............................ O-ring or seal adhesive is needed.
- Screw hole area .......................... Screws should have a thread lock (LOCTITE® 242 is recommended) or seal adhesive.

(Note) If you use Harmonic Grease 4BNo.2, strict sealing is required.

Assembly precautions

The wave generator is installed after the flexspline and circular spline. If the wave generator is not inserted into the flexspline last, gear teeth scuffing damage or improper eccentric gear mesh may result. Installation resulting in an eccentric tooth mesh (Dedoidal) will cause noise and vibration, and can lead to early failure of the gear. For proper function, the teeth of the flexspline and Circular Spline mesh symmetrically.

■ Precautions on the wave generator

1. Avoid applying undue axial force to the wave generator during installation. Rotating the wave generator bearing while inserting it is recommended and will ease the process.
2. If the wave generator does not have an Oldham coupling, extra care must be given to ensure that concentricity and inclination are within the specified limits.

■ Precautions on the circular spline

The circular Spline must not be deformed in any way during the assembly. It is particularly important that the mounting surfaces are prepared correctly.

1. Mounting surfaces need to have adequate flatness, smoothness, and no distortion.
2. Especially in the area of the screw holes, burrs or foreign matter should not be present.
3. Adequate relief in the housing corners is needed to prevent interference with the corner of the circular spline.
4. The circular spline should be rotatable within the housing. Be sure there is not interference and that it does not catch on anything.
5. When a bolt is inserted into a bolt hole during installation, make sure that the bolt fits securely and is not in an improper position or inclination.
6. Do not apply torque at recommended torque all at once. First, apply torque at about half of the recommended value to all bolts, then tighten at recommended torque. Order of tightening bolts must be diagonal.
7. Avoid pinning the circular spline if possible as it can reduce the rotational precision and smoothness of operation.

■ Precautions on the flexspline

1. Mounting surfaces need to have adequate flatness, smoothness, and no distortion.
2. Especially in the area of the screw holes, burrs or foreign matter should not be present.
3. Adequate clearance with the housing is needed to ensure no interference especially with the major axis of flexspline.
4. Bolts should rotate freely when installing through the mounting holes of the flexspline and should not have any irregularity due to the shaft bolt holes being misaligned or oblique.
5. Do not tighten the bolts with the specified torque all at once. Tighten the bolts temporarily with about half the specified torque, and then tighten them to the specified torque. Tighten them in an even, crisscross pattern.
6. The flexspline and circular spline are concentric after assembly. After installing the wave generator bearing, if it rotates in an unbalanced way, check the mounting for dedoidal or non-concentric installation.
7. Care should be taken not to damage the flexspline diaphragm or gear teeth during assembly. Avoid hitting the tips of the flexspline teeth and circular spline teeth. Avoid installing the CS from the open side of the flexspline after the wave generator has been installed.

■ Rust prevention

Although the Harmonic Drive® gears come with some corrosion protection, the gear can rust if exposed to the environment. The gear external surfaces typically have only a temporary corrosion inhibitor and some oil applied. If an anti-rust product is needed, please contact us to review the options.
"Dedoidal" state

It is normal for the flexspline to engage with the circular spline symmetrically as shown in Figure 029-1. However, if the ratcheting phenomenon, which is described on Page 013, is caused or if the three parts are forcibly inserted and assembled, engagement of the teeth may be out of alignment as shown in Figure 029-2. This is called "dedoidal". Note: Early failure of the gear will occur.

How to check "dedoidal"

By performing the following methods, check whether the gear engagement is "dedoidal".

(1) Judging by the irregular torque generated when the wave generator turns

1) Slowly turn the input shaft with your hand in a no-load condition. If you can turn it with average force, it is normal. If it turns irregularly, it may be "dedoidal".

2) Turn the wave generator in a no-load condition if it is attached to a motor. If the average current value of the motor is about 2 to 3 times the normal value, it may be "dedoidal".

(2) Judging by measuring vibration on the body of the flexspline

The scale deflection of the dial gauge draws a sine wave as shown by the solid line in Graph 029-3 when it is normally assembled. When "dedoidal" occurs, the gauge draws a deflected wave shown by the dotted line as the flexspline is out of alignment.
Checking Output Bearing

A precision cross roller bearing is built in the unit type and the gear head type to directly support the external load (output flange) (precision 4-point contact ball bearing for the CSF-mini series).

Please calculate maximum moment load, life of cross roller bearing, and static safety factor to fully maximize the performance of a housed unit (gearhead).

See the corresponding pages on each series for cross roller bearing specifications.

Checking procedure

(1) Checking the maximum moment load (M_{max})

Calculate maximum moment load (M_{max}).

Maximum moment load \( M_{max} \leq \text{allowable moment} (M_c) \)

(2) Checking the life

Calculate the radial load (F_{rav}) and the average axial load (F_{av}).

Calculate the radial load coefficient (x) and the axial load coefficient (y).

Calculate lifetime

(3) Checking the static safety coefficient

Calculate the static equivalent radial load coefficient (P_o).

Check the static safety coefficient. (f_s)

How to calculate the maximum moment load

Maximum moment load \( M_{max} \) is obtained as follows.

Make sure that \( M_{max} \leq M_c \).

\[
M_{max} = F_{rav}(L_r+R)+F_{av} \cdot L_a
\]

How to calculate the average load

When the radial load and axial load vary, the life of cross roller bearing can be determined by converting to an average load.

How to calculate the average radial load (F_{rav})

How to calculate the average axial load (F_{av})

How to calculate the average output speed (N_{av})

How to calculate the radial load coefficient (X) and axial load coefficient (Y)

Symbols for Formula 030-1

Table 030-1

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Description</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>F_{rmax}</td>
<td>Max. radial load</td>
<td>N(kgf)</td>
</tr>
<tr>
<td>F_{av}</td>
<td>Max. axial load</td>
<td>N(kgf)</td>
</tr>
<tr>
<td>Lr, La</td>
<td>Offset amount</td>
<td>m</td>
</tr>
<tr>
<td>R</td>
<td>Offset amount</td>
<td>m</td>
</tr>
</tbody>
</table>

See Fig. 030-1. See Formula 030-1.
How to calculate the average load

(Average radial load, average axial load, average output speed)

When the radial load and axial load vary, the life of cross roller bearing can be determined by converting to an average load.

How to calculate the average radial load (Frav)

\[
Fr_{av} = \frac{n_1 Fr_1 + n_2 Fr_2 + \cdots + n_t Fr_t}{n_1 + n_2 + \cdots + n_t}
\]

How to calculate the average axial load (Fav)

\[
F_{av} = \frac{n_1 Fa_1 + n_2 Fa_2 + \cdots + n_t Fa_t}{n_1 + n_2 + \cdots + n_t}
\]

How to calculate the average output speed (Nav)

\[
Nav = \frac{n_1 t_1 + n_2 t_2 + \cdots + n_t t_t}{t_1 + t_2 + \cdots + t_t}
\]

How to calculate the radial load coefficient (X) and axial load coefficient (Y)

\[
X = \frac{F_{av+2} (Frav (Lr + R) + F_{av} \cdot La)}{dp}
\]

Symbol for Formula 031-4

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Frav</td>
<td>Average radial load (N(kgf))</td>
</tr>
<tr>
<td>Fav</td>
<td>Average axial load (N(kgf))</td>
</tr>
<tr>
<td>Lr, La</td>
<td>Offset amount (m)</td>
</tr>
<tr>
<td>R</td>
<td>Pitch circle diameter of a roller (m)</td>
</tr>
</tbody>
</table>

Note that the maximum radial load in ti is Fr1 and the maximum radial load in ti is Fr3.

Note that the maximum axial load in ti is Fa1 and the maximum axial load in ti is Fa3.

Graph 031-1
Life of the output bearing

Calculate life of the output bearing by Formula 032-1.
You can calculate the dynamic equivalent radial load (Pc) by Formula 032-2.

Formula 032-1

\[
L_{10} = \frac{10^9}{60 \times N_{av}} \times \left( C \frac{F_{av} \cdot F_{pc}}{f_{w} \cdot P_{c}} \right)^{0.3}
\]

Formula 032-2

\[
P_{c} = X \cdot \left( F_{av} + \frac{2(F_{av} \cdot X + F_{av} \cdot Y)}{d \cdot F_{av}} \right) + Y \cdot F_{av}
\]

Symbols for Formula 032-1

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>L&lt;sub&gt;10&lt;/sub&gt;</td>
<td>Life in hours</td>
</tr>
<tr>
<td>N&lt;sub&gt;av&lt;/sub&gt;</td>
<td>Average output rated load speed (rpm)</td>
</tr>
<tr>
<td>C</td>
<td>Basic dynamic rated load (N [kgf])</td>
</tr>
<tr>
<td>P&lt;sub&gt;c&lt;/sub&gt;</td>
<td>Dynamic equivalent (N [kgf])</td>
</tr>
<tr>
<td>f&lt;sub&gt;w&lt;/sub&gt;</td>
<td>Load coefficient ——</td>
</tr>
</tbody>
</table>

Symbols for Formula 032-2

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>F&lt;sub&gt;av&lt;/sub&gt;</td>
<td>Average radial load (N [kgf])</td>
</tr>
<tr>
<td>F&lt;sub&gt;av&lt;/sub&gt;</td>
<td>Average axial load (N [kgf])</td>
</tr>
<tr>
<td>d&lt;sub&gt;p&lt;/sub&gt;</td>
<td>Pitch circle diameter (m)</td>
</tr>
<tr>
<td>X</td>
<td>Radial load coefficient ——</td>
</tr>
<tr>
<td>Y</td>
<td>Axial load coefficient ——</td>
</tr>
<tr>
<td>L&lt;sub&gt;r&lt;/sub&gt;, L&lt;sub&gt;a&lt;/sub&gt;</td>
<td>—— m</td>
</tr>
<tr>
<td>R</td>
<td>Offset (m)</td>
</tr>
<tr>
<td>M&lt;sub&gt;ave&lt;/sub&gt;</td>
<td>Average moment load (Nm)</td>
</tr>
</tbody>
</table>

Load coefficient

<table>
<thead>
<tr>
<th>Load status</th>
<th>f&lt;sub&gt;w&lt;/sub&gt;</th>
</tr>
</thead>
<tbody>
<tr>
<td>Steady operation without impact and vibration</td>
<td>1 to 1.2</td>
</tr>
<tr>
<td>Normal operation</td>
<td>1.2 to 1.5</td>
</tr>
<tr>
<td>Operation with impact and vibration</td>
<td>1.5 to 3</td>
</tr>
</tbody>
</table>

See "How to calculate the average load." See Formula 031-1.
See "How to calculate the average load." See Formula 031-2.
See Fig. 030-1 and "Specification of the output bearing" of each series.
See Formula 031-4.
See Figure 030-1. See Fig. 030-1 and "Specification of the output bearing" of each series.
See Fig. 030-1 and "Specification of the output bearing" of each series.
How to calculate life during oscillating motion

Calculate the life of the cross roller bearing during oscillating motion by Formula 033-1.

\[
\text{Loc} = \frac{10^6}{60 \times n_1} \times \frac{90}{\theta} \times \left( \frac{C}{f_{\text{w}} + P_{\text{c}}} \right)^{1/3}
\]

Table 033-1

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Description</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>Loc</td>
<td>Rated life for oscillating motion</td>
<td>hour</td>
</tr>
<tr>
<td>n1</td>
<td>Round trip oscillation each minute</td>
<td>cpm</td>
</tr>
<tr>
<td>C</td>
<td>Basic dynamic rated load</td>
<td>N/\text{kgf}</td>
</tr>
<tr>
<td>P_{\text{c}}</td>
<td>Dynamic equivalent radial load</td>
<td>N/\text{kgf}</td>
</tr>
<tr>
<td>f_{\text{w}}</td>
<td>Load coefficient</td>
<td>---</td>
</tr>
<tr>
<td>\theta</td>
<td>Oscillating angle /2</td>
<td>Degree</td>
</tr>
</tbody>
</table>

(Note) A small angle of oscillation (less than 5 degrees) may cause fretting corrosion to occur since lubrication may not circulate properly. Contact us if this happens.
**How to calculate the static safety coefficient**

Basic static rated load is an allowable limit for static load, but its limit is determined by usage. In this case, static safety coefficient of the cross roller bearing can be calculated by Formula 034-2.

\[
fs = \frac{Co}{Po}
\]

\[
Po = F_{rmax} + \frac{2M_{max}}{dp} + 0.44Fa_{max}
\]

**Symbols for Formula 034-1**

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Co</td>
<td>Basic static rated load (N(kgf))</td>
</tr>
<tr>
<td>Po</td>
<td>Static equivalent radial load (N(kgf))</td>
</tr>
</tbody>
</table>

See "Specification of the output bearing" of each series.

**Symbols for Formula 034-2**

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>F_{rmax}</td>
<td>Max. radial load (N(kgf))</td>
</tr>
<tr>
<td>F_{aax}</td>
<td>Max. axial load (N(kgf))</td>
</tr>
<tr>
<td>M_{max}</td>
<td>Max. moment load (Nm(kgfm))</td>
</tr>
</tbody>
</table>

See "How to calculate the maximum moment load" on Page 030.

**Static Safety Coefficient**

<table>
<thead>
<tr>
<th>Condition</th>
<th>fs</th>
</tr>
</thead>
<tbody>
<tr>
<td>When high rotation precision is required</td>
<td>≥3</td>
</tr>
<tr>
<td>When shock and vibration are expected</td>
<td>≥2</td>
</tr>
<tr>
<td>Under normal operating condition</td>
<td>≥1.5</td>
</tr>
</tbody>
</table>

See Fig. 030-1 and "Specification of the output bearing" of each series.
HarmonicDrive® Reducer for Precision Control

For Safe Use of Harmonic Drive® Component
Set and Gear Unit

⚠️ Warning: Means that improper use or handling could result in a risk of death or serious injury.

⚠️ Caution: Means that improper use or handling could result in personal injury or damage to property.

Limited Applications

This product cannot be used for the following applications:
- Space equipment
- Aircraft equipment
- Nuclear power equipment
- Game equipment
- Equipment and apparatus used in domestic homes
- Equipment that directly works on human bodies
- Equipment for transport of humans
- Equipment for use in a special environment

Please consult Harmonic Drive beforehand when intending to use one of its product for the aforementioned applications.

Install a safety device that avoids an accident even if output of this product becomes uncontrollable due to breakdown when using it in equipment that affects human lives and that may trigger serious damage.

<table>
<thead>
<tr>
<th>Design Precaution: Be certain to read the catalog when designing your equipment.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Use only in a specified environment.</td>
</tr>
<tr>
<td>⬜ Please ensure the following environmental conditions are complied with:</td>
</tr>
<tr>
<td>- Ambient temperature 0 to 40°C</td>
</tr>
<tr>
<td>- No splashing of water or oil</td>
</tr>
<tr>
<td>- Do not expose to corrosive or explosive gas</td>
</tr>
<tr>
<td>- No dust such as metal powder</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Operational Precaution: Be certain to read the catalog before operating the equipment.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Be careful in handling products and parts.</td>
</tr>
<tr>
<td>⬜ Do not impact the parts and units with a hammer, etc. Do not scratch or dent them. Possible damage is assumed.</td>
</tr>
<tr>
<td>⬜ If you use the equipment in a damaged condition, the specified performance may not be retained. It can also cause troubles such as breakdown.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Handling lubricant</th>
</tr>
</thead>
<tbody>
<tr>
<td>Precautions on handling lubricant</td>
</tr>
<tr>
<td>⬜ Use protective eyewear when handling. Avoid contact with eyes. May cause inflammation.</td>
</tr>
<tr>
<td>⬜ Use gloves and other skin protection when handling. Avoid contact with skin. May cause inflammation.</td>
</tr>
<tr>
<td>⬜ Do not swallow. May cause diarrhea and vomiting.</td>
</tr>
<tr>
<td>⬜ Keep out of reach of children.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Handling lubricant</th>
</tr>
</thead>
<tbody>
<tr>
<td>First-aid</td>
</tr>
<tr>
<td>⬜ EYES: Flush with clean water for at least 15 minutes. Consult a physician.</td>
</tr>
<tr>
<td>⬜ SKIN: Thoroughly remove with cloth or paper and wash with soap and water.</td>
</tr>
<tr>
<td>⬜ NGESTION: Consult a physician immediately. Do not induce vomiting.</td>
</tr>
<tr>
<td>⬜ INHALATION: Immediately seek fresh air if adverse effects are observed.</td>
</tr>
</tbody>
</table>

⚠️ Caution: Please discard as industrial waste.

⚠️ Caution: Please discard as industrial waste when discarding.