

HarmonicDrive®

MECHATRONICS

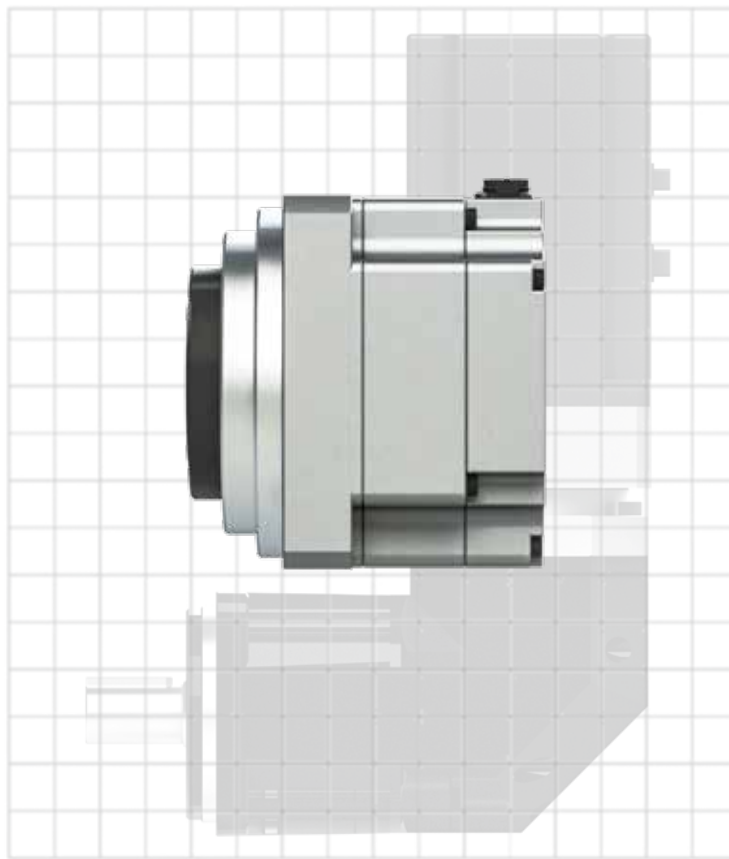
AC Servo Actuator

FPA Series

Reduced overall
length

High
performance

Energy-
saving



Solving the Challenges of Orthogonal Shaft Planetary Gears and Offering Further Benefits

The AC Servo Actuator FPA Series combines the precision planetary gear speed reducer HarmonicPlanetary® with a dedicated AC servo motor.

With its flat, thin profile, the FPA Series reduces overall length compared with combinations of orthogonal shaft type speed reducers and servo motors in the same torque range.

The absence of an orthogonal section simultaneously achieves high efficiency and precision. Expected performance improvements include further miniaturization of semiconductor/FPD manufacturing equipment, robots, machine tools, and various FA equipment, as well as enhanced precision and efficiency for all equipment using orthogonal planetary speed reducers. In addition to the dedicated HA-900 series driver, it is also compatible with Mitsubishi Electric's MELSERVO J5 series and Panasonic's MINAS A6 series.

Features

◆ Flat and Low Profile

The precision planetary gear speed reducer HarmonicPlanetary® and flat AC servo motor are coaxially integrated, achieving a flat profile. This design allows for a shorter overall length and further miniaturization of equipment.

◆ Low Loss

The absence of an orthogonal gear section minimizes energy loss.

◆ High Stiffness, Low Backlash

It features the high-stiffness HarmonicPlanetary® HPG series. Backlash is less than one minute (less than three minutes for size 11). The unique "thin-walled elastic internal gear" design ensures minimal backlash variation.

◆ Wide Speed-Torque Characteristics Allow for Various Operating Conditions

Reduction ratios range from 1/5 to 1/45. This allows for selection based on required speed and torque for a wide range of applications.

◆ 24-bit Absolute Encoder

It is equipped with a 24-bit absolute encoder that supports A-format®* serial communication. The encoder features multi-turn counting, which is essential for actuators with speed reducers, and it maintains absolute position.

* "A-format" is a registered trademark of Nikon Corporation.

◆ Quick-Lock Connector

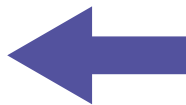
It features a lever lock-type connector for easy wiring. The motor power cable and encoder signal cable connectors are integrated, enabling quick extension cable installation.

Eliminating the Disadvantages of Orthogonal Shaft Planetary Gears

The optimal design of our proprietary planetary speed reducer and motor reduces the overall length and eliminates the disadvantages of orthogonal shaft planetary gears.

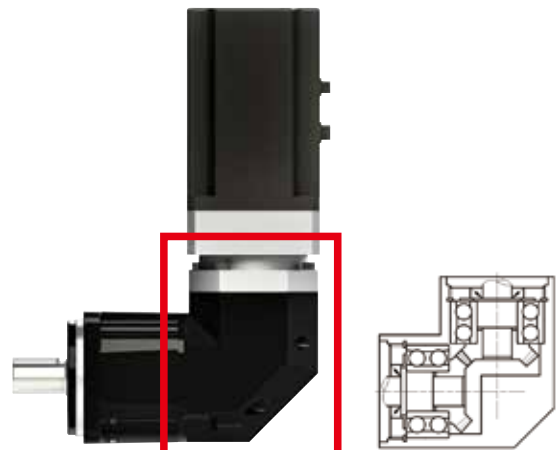
The Reduced Overall Length Eliminates the need for an Orthogonal Gear

- Low Energy Loss
- Low Backlash



Disadvantages of Orthogonal Gears

- High Energy Loss
- High Backlash



Orthogonal Gear Section

Bearings for two shafts, oil seals, spiral bevel gears, and high-viscosity grease are required on the high-speed shaft side, resulting in high energy loss.

Specifications

Type Item			FPA11A*		FPA14A		FPA20A		FPA32A	
			05	11	15	33	05	11	21	45
			F08A200				F12A200			
Combined driver			HA-900A-3A-200				HA-900A-6A-200			
Maximum torque ^{*1}		N·m	7.8	18	23	23	32	71	135	294
Limit for continuous torque ^{*1,2}		N·m	2.3	5.0	7.1	10	9.7	20	40	90
Maximum speed ^{*1}		rpm	1200	545.4	400	181.8	960	436.3	228.5	106.6
Torque constant ^{*1}		N·m/A	1.7	3.7	5.0	11.0	2.1	4.6	8.8	18.8
Maximum current ^{*1}		A	5.8	6.1	5.7	2.7	18	18	18	18
Limit for continuous current ^{*1,2}		A	1.8	1.8	1.8	1.2	5.5	5.1	5.3	5.5
Inductive voltage constant ^{*3}		V/(rpm)	0.19	0.41	0.56	1.2	0.23	0.5	0.95	2.0
Phase resistance (20°C)		Ω		1.4			0.33			
Phase inductance		mH		2.5			1.4			
Moment of inertia ^{*4}	GD ² /4	kg·m ²	0.0011	0.0059	0.011	0.052	0.0096	0.045	0.17	0.76
Reduction ratio			1:5	1:11	1:15	1:33	1:5	1:11	1:21	1:45
Limit for moment load		N·m	9.5	32.3			183		452	
Moment stiffness		N·m/rad	0.88	3.0 x 10 ⁴			16.8×10 ⁴		42.1 x 10 ⁴	
Unidirectional positioning accuracy		minutes	5	4	4	4	5	4	4	4
Encoder type				Absolute encoder						
Encoder resolution		Single-turn detector		2 ²⁴ (16777216)						
		Multi-turn detector ^{*5}		2 ¹⁶ (65536)						
Output shaft resolution		Pulse/Revolution	83886080	184549376	251658240	553648128	83886080	184549376	352321536	754974720
Weight ^{*4}		kg	1.6	2.2	2.2	2.2	5.6	5.8	7.4	7.4
Ambient environmental conditions ^{*6}			Use temperature: 0 to 40°C / Storage temperature: −20 to 60°C, Use humidity and storage humidity: 20 to 80%RH (non-condensing) Vibration resistance: 25m/s ² (frequency: 10 to 400 Hz) / impact resistance: 300 m/s ²⁻⁷ No dust, metal powder, corrosive gas, flammable gas, oil mist, or other similar material. Place indoors without being exposed to direct sunlight. Altitude: 1000 m or less							
Motor insulation			Insulation resistance: 100 MΩ or higher (500 VDC), Dielectric strength: 1500 VAC / 1 min, Heat resistance class: Class A							
Mounting direction			Can be installed in any direction.							
Protective structure			Totally enclosed self-cooled type (IP54)							

The values in the table above show typical values.

*1: They are typical characteristics in the case of combinations with our driver (driven with the ideal sine wave).

*2: This is the value for saturated temperature when installed on the aluminum heatsink of the following size:

FPA11Axx-F08: 320×320×16 [mm], FPA14Axx-F08: 320×320×16 [mm], FPA20Axx-F12: 400×400×20 [mm], FPA32Axx-F12: 400×400×20 [mm]

*3: The value of the phase MEF constant multiplied by 3.

*4: Value for the flange output type. For the straight shaft type, refer to the technical material, "4-1 Options."

*5: The range of the multi-turn detection is from -32768 to 32767.

*6: For details, refer to the technical material "3-3 Installation location and installation work."

*7: For test conditions, refer to technical materials "1-11 Impact resistance" and "1-12 Vibration resistance." This value is not ensured if vibrations or shocks are applied for hours or continuously.

* The FPA11A will be released soon.

Ordering Code

FPA	14	A	11	F0	HG	-	F	08	A	200	-	32	S	24b	A	-	C	-	
(1)	(2)	(3)	(4)	(5)	(6)	(7)	(8)	(9)	(10)	(11)	(12)	(13)	(14)	(15)	(16)				

(1)	Model name	AC servo actuator FPA series
(2)	Size	11, 14, 20, 32
(3)	Version symbol	A
(4)	Reduction ratio	05: 1/5 (Sizes 11 and 20) 11: 1/11 (Sizes 14 and 20) 15: 1/15 (Size 14) 21: 1/21 (Size 32) 33: 1/33 (Size 14) 45: 1/45 (Size 32)
(5)	Output shaft form symbol	F0: (Sizes 11, 14, 20, 32) Flange output J20: (Size 11) Straight shaft, no keyway J60: (Size 11) Straight shaft, with key, with center tap J2: (Sizes 14, 20, 32) Straight shaft, no keyway J6: (Sizes 14, 20, 32) Straight shaft, with key, with center tap
(6)	Speed reducer type	HG: Planetary Speed Reducer HPG series

These sizes apply when combined with our HA-900 driver.

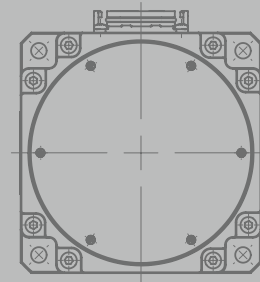
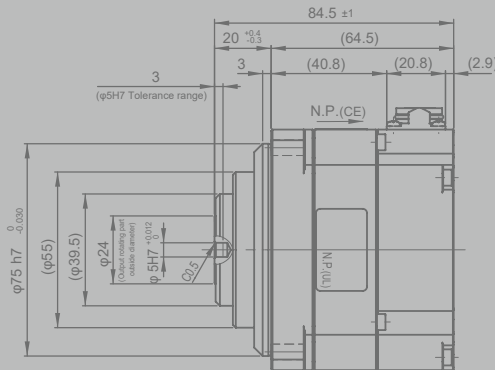
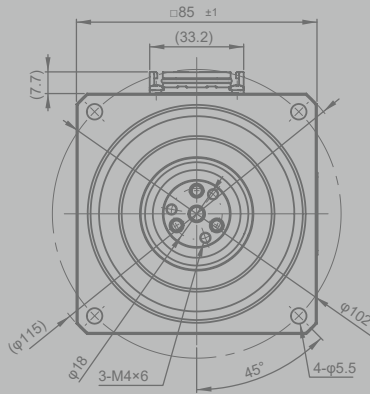
For sizes when combined with drivers from other manufacturers, please contact us.

(7)	Motor version symbol	F
(8)	Motor size	08: Size 11, 14 12: Size 20, 32
(9)	Brake (for holding)	A: Not equipped with a brake
(10)	Input voltage of the applied servo driver	200: 200V
(11)	Encoder type	32: A-format compliant, Transmission rate: 4 Mbps, 1-to-1 connection
(12)	Encoder type	S: Multi-turn absolute (External battery backup system)
(13)	Encoder resolution	24b: 24-bit (16,777,216 pulses/revolution)
(14)	Encoder phase angle	Phase difference between the induced voltage of the motor U phase and the absolute encoder origin A: 0 degrees
(15)	Connector specification	C: Equipped with the the standard connector
(16)	Special specifications	No symbol: Standard product SP: Special-specification product

(Please inquire regarding UL compliance for special specifications and options.)

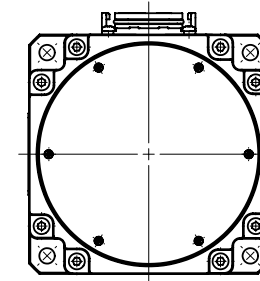
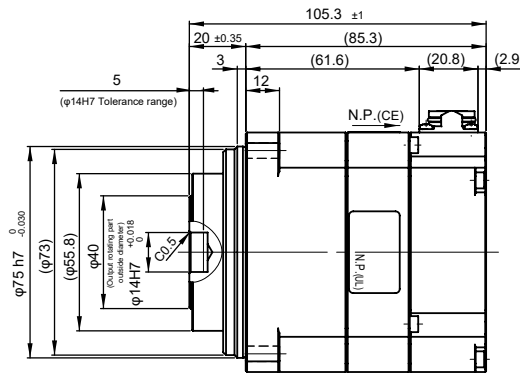
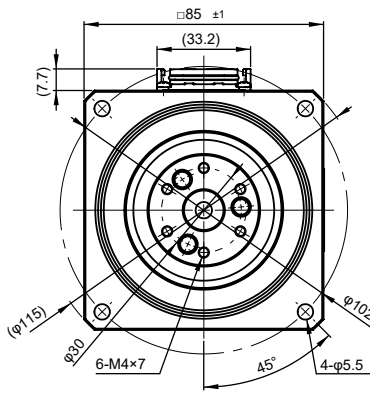
External Dimensions

FPA11A



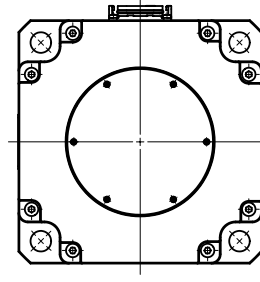
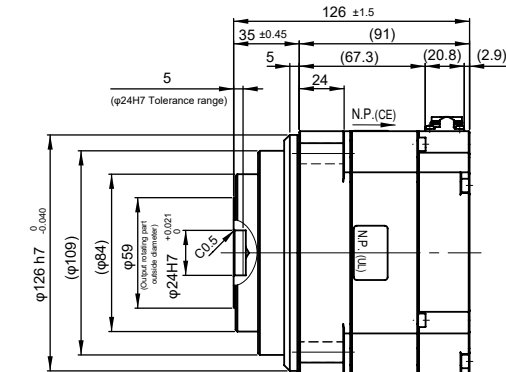
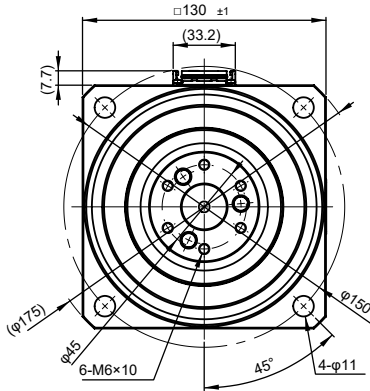
Unit [mm]
Third angle projection

FPA14A



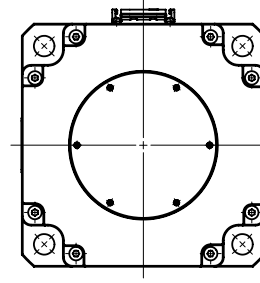
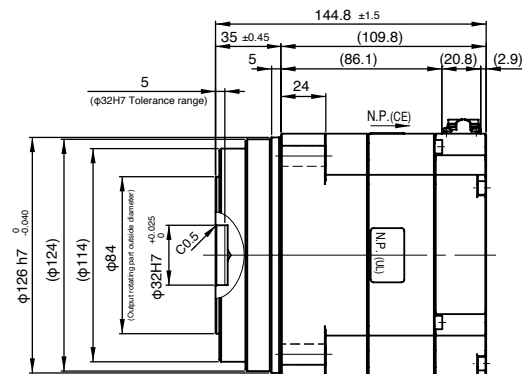
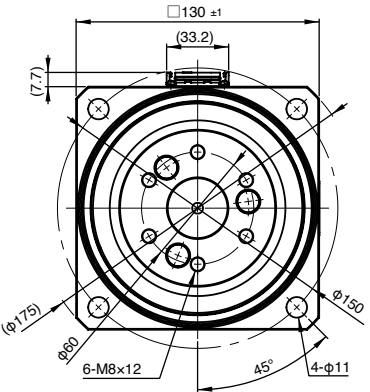
Unit [mm]
Third angle projection

FPA20A



Unit [mm]
Third angle projection

FPA32A



Unit [mm]
Third angle projection

Note: For details of the external dimensions, refer to the delivery specification drawing issued by HDS. The tolerance varies depending on the manufacturing method (casting or machining) of the parts. For more information on the tolerance of a dimension without a tolerance, please contact us.
* The FPA11A will be released soon.

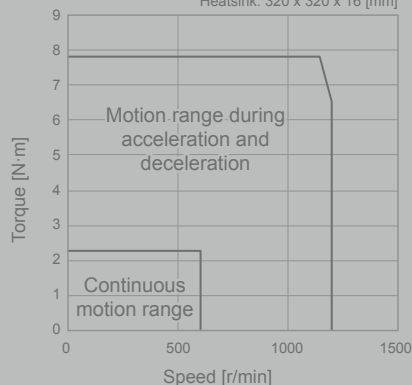
Operable Range

- * The data applies when it is combined with our HA-900 driver.
- * The continuous operating range is the value obtained when mounted on an aluminum heat sink of the size shown in the upper right corner of the graph.
- * This is the representative value for three-phase 200V.

FPA11A

FPA11A05-F08

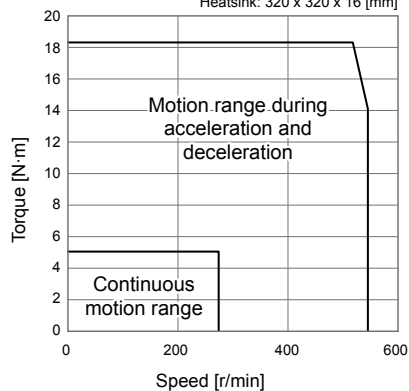
Heatsink: 320 x 320 x 16 [mm]



FPA14A

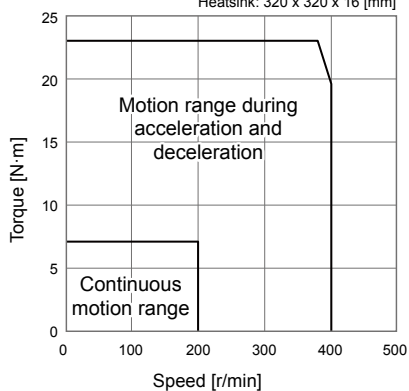
FPA14A11-F08

Heatsink: 320 x 320 x 16 [mm]



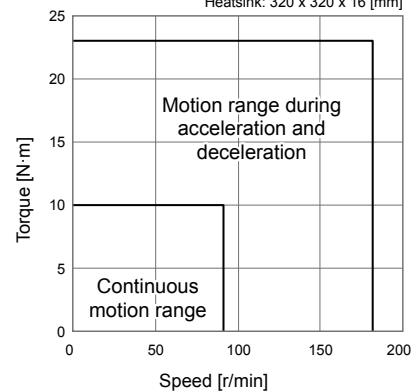
FPA14A15-F08

Heatsink: 320 x 320 x 16 [mm]



FPA14A33-F08

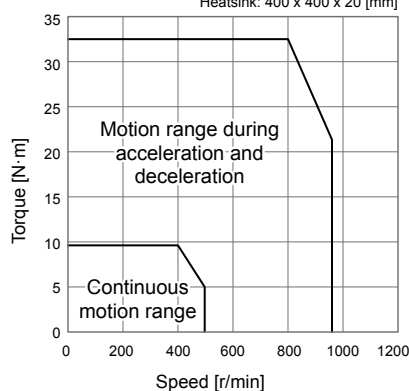
Heatsink: 320 x 320 x 16 [mm]



FPA20A

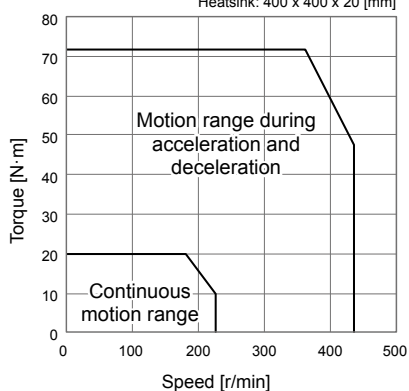
FPA20A05-F12

Heatsink: 400 x 400 x 20 [mm]



FPA20A11-F12

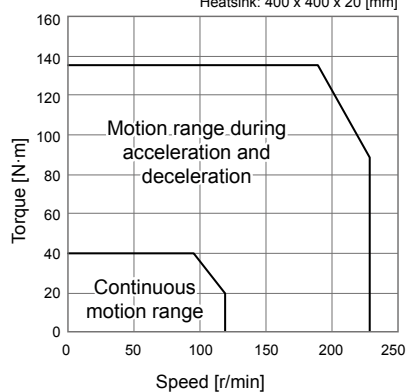
Heatsink: 400 x 400 x 20 [mm]



FPA32A

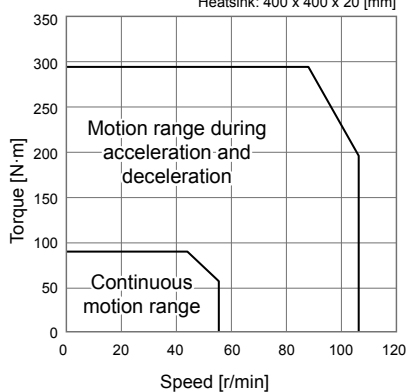
FPA32A21-F12

Heatsink: 400 x 400 x 20 [mm]



FPA32A45-F12

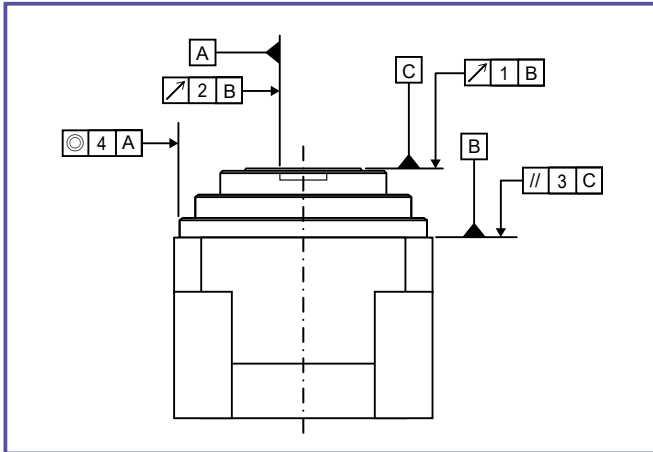
Heatsink: 400 x 400 x 20 [mm]



Mechanical Accuracy

The FPA series actuator output shaft and mechanical accuracy of the mounting flange are shown below:

Standard



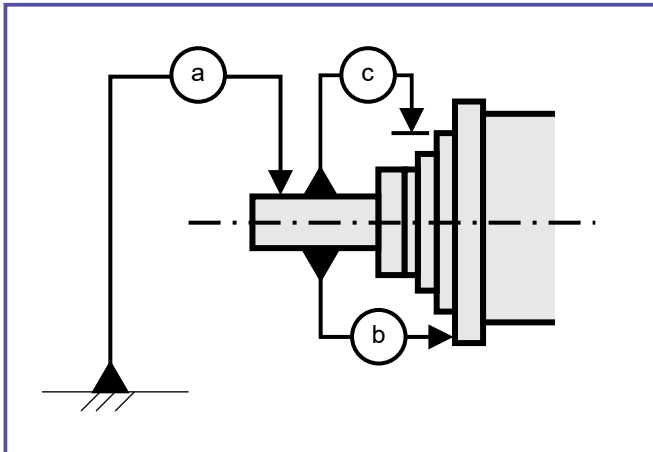
Unit: mm

Accuracy Item	FPA11A*	FPA14A	FPA20A	FPA32A
1. Output shaft surface runout	0.020	0.020	0.020	0.020
2. Output shaft radial runout	0.030	0.040	0.040	0.040
3. Parallelism between output shaft and mounted surface	0.050	0.060	0.060	0.060
4. Concentricity between output shaft and fitting part	0.040	0.050	0.050	0.050

Note: Values are based on the Total Indicator Reading (T.I.R.).

* The FPA11A will be released soon.

With Straight Shaft



Unit: mm

Accuracy Item	FPA11A*	FPA14A	FPA20A	FPA32A
a. Output shaft axial runout	0.030	0.040	0.040	0.040
b. Surface runout of mounted surface	0.050	0.060	0.060	0.060
c. Concentricity between the output shaft and the fitting part	0.040	0.050	0.050	0.050

Note 1: Values are based on the Total Indicator Reading (T.I.R.).

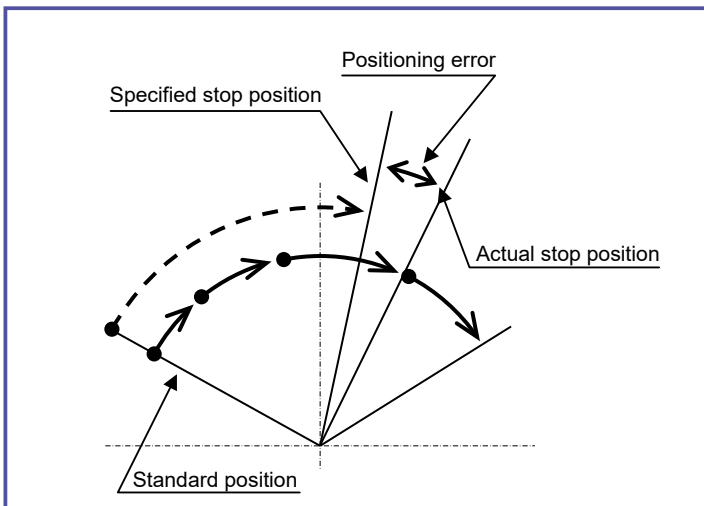
Note 2: For detailed dimensions of the actuator, refer to the delivery specification drawings.

Note 3: The output shaft has not been surface-treated.

* The FPA11A will be released soon.

Unidirectional Positioning Accuracy

"Unidirectional positioning accuracy" refers to the maximum value in one revolution of the values that are calculated from the difference between the actually revolved angle and the specified revolved angle from the standard position at each of the points positioned in the fixed rotational direction (JIS B 6201-1987). The FPA series incorporates the planetary gear speed reducer HarmonicPlanetary® HPG series, which reduces the effect of motor shaft positioning error to 1/reduction ratio.



The "unidirectional positioning accuracy" for each size is shown below.

Units: minutes

Reduction ratio	Type	FPA11A*	FPA14A	FPA20A	FPA32A
1:5		5	-	5	-
1:11		-	4	4	-
1:15		-	4	-	-
1:21		-	-	-	4
1:33		-	4	-	-
1:45		-	-	-	4

* The FPA11A will be released soon.

Relay Cable

The relay cables connect the FPA series and the HA-900 series driver. The actuator-side connector combines the motor and encoder connections for quick installation. Please select one of the three specifications based on the cable exit direction. A relay cable is required for connecting the FPA series and the HA-900 series driver.

■ Ordering Code

EWE-MBS ●● – HR0608A – TN4 – MDR14

Cable direction

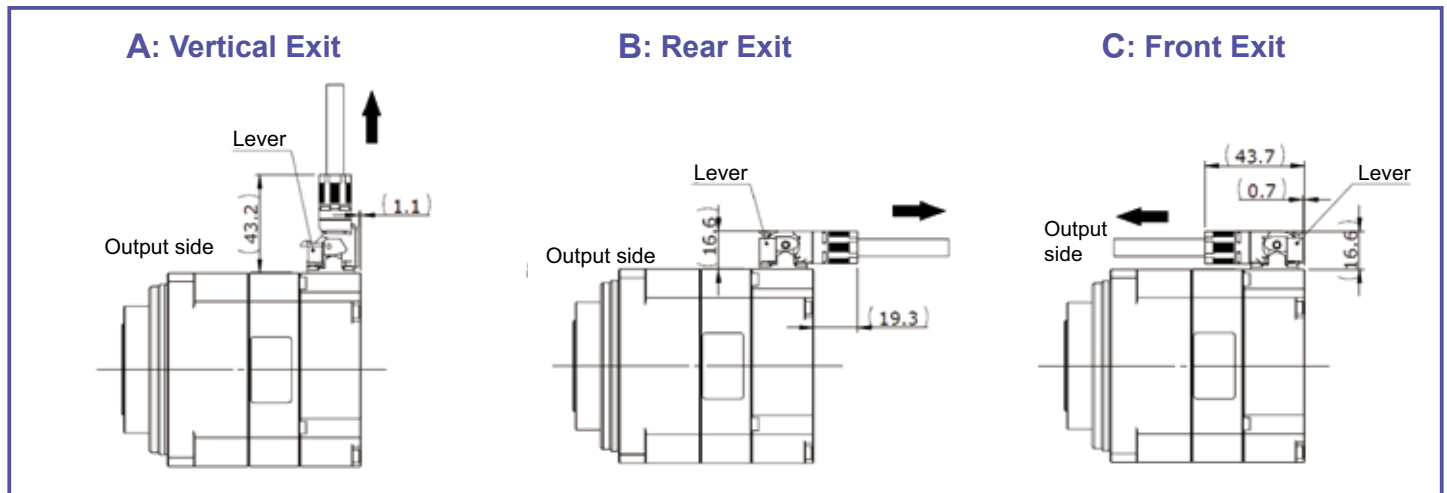
Cable length

Symbol	Specifications
A	(All sizes) Vertical exit type
B	(All sizes) Rear exit type
C	(All sizes) Front exit type*

* Size 11 requires cable bending space.

Symbol	Specifications
02	2 m
05	5 m
10	10 m

■ Installation Diagram/Outline Drawing



Design and Installation Precautions

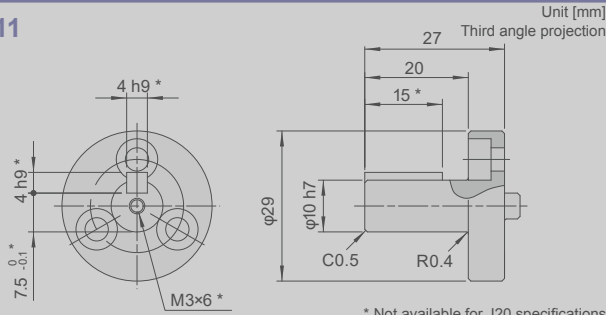
- Ensure that the cable is routed with a sufficient bending radius. (For fixed sections, use a bend radius of at least four times the cable diameter. For moving sections, use a bend radius of at least six times the cable diameter.)
- When using the front exit type, pay attention to the shape of customer-installed parts to ensure there is enough space for the cable to be routed properly. For size 11 in particular, the product mounting surface and the connector cable exit point are close together. If necessary, incorporate clearance into the customer parts.
- When attaching the relay cable connector to the actuator, visually confirm that the lever clicks into place securely so that the lever is surely locked.

Options

With straight shaft (Output shaft form symbols: J20, J60, J2, J6)

Straight-type output shafts are available. They are assembled onto the product and shipped.

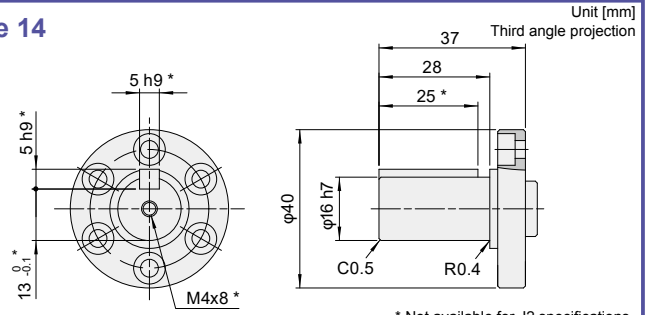
Size 11



* Not available for J20 specifications

Symbol	Specifications	Attachments
J20	Straight shaft, no keyway	-
J60	Straight shaft, with key, with center tap	Parallel key: 4h9x49x15L (single pointed)

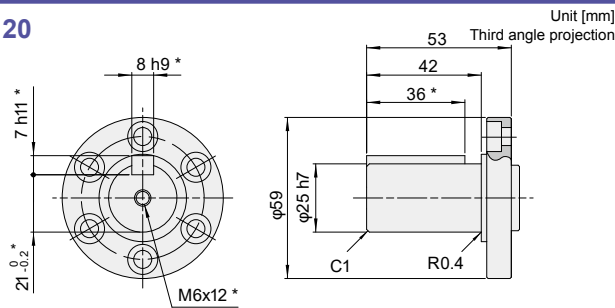
Size 14



* Not available for J2 specifications

Symbol	Specifications	Attachments
J2	Straight shaft, no keyway	-
J6	Straight shaft, with key, with center tap	Parallel key: 5h9x5h9x25L (single pointed)

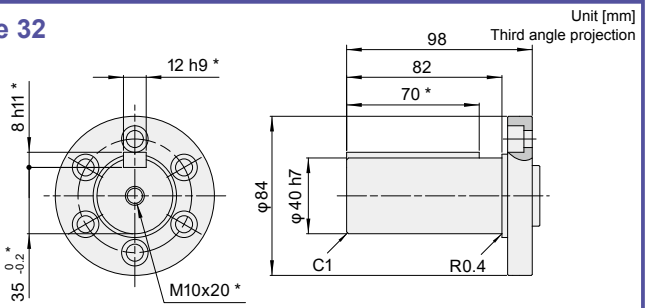
Size 20



* Not available for J2 specifications

Symbol	Specifications	Attachments
J2	Straight shaft, no keyway	-
J6	Straight shaft, with key, with center tap	Parallel key: 8h9x7h11x36L (single pointed)

Size 32



* Not available for J2 specifications

Symbol	Specifications	Attachments
J2	Straight shaft, no keyway	-
J6	Straight shaft, with key, with center tap	Parallel key: 12h9x8h11x70L (single pointed)

* The straight shaft option for this product is assembled and shipped by HDSI. Since it cannot be locked in rotation, it is difficult for the customer to retrofit it.

* The FPA11A will be released soon.

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"HarmonicDrive®" is a trademark of Harmonic Drive Systems Inc. The academic or general nomenclature of our products HarmonicDrive® is strain wave gearing.

All specifications and dimensions in this manual subject to change without notice. This manual is correct as of July 2026.

TI-26018 REV 1 FPA Brochure 072026

